# Lower Semicontinuity, Almost Lower Semicontinuity, and Continuous Selections for Set-Valued Mappings 

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#### Abstract

For a set-valued mapping, the relationships between lower semicontinuity, almost lower semicontinuity, and the existence of various kinds of continuous selections for the mapping are explored. For the spaces $C_{0}(T)$ and $L_{1}$, intrinsic characterizations are given of the one-dimensional subspaces whose metric projections admit continuous selections. © 1988 Academic Press, Inc.


## 1. Introduction

Let $X$ be a paracompact space, $Y$ a normed linear space, $2^{Y}$ the collection of all nonempty subsets of $Y$, and $\mathscr{C}(Y)$ the collection of all nonempty, closed, and convex subsets of $Y$. The $\varepsilon$-neighborhood of a set $A \in 2^{r}$ is defined by

$$
B_{\varepsilon}(A):=\{y \in Y \mid d(y, A)<\varepsilon\}, \quad \text { where } \quad d(y, A):=\inf \{\|y-a\| \mid a \in A\} .
$$

A function $F: X \rightarrow 2^{Y}$ is called a set-valued (or multivalued) mapping

[^0]from $X$ into $Y$. $F$ is called lower semicontinuous (1.s.c.) at a point $x_{0} \in X$ if whenever $W$ is an open set in $Y$ with $F\left(x_{0}\right) \cap W \neq \varnothing$, there exists a neighborhood $U$ of $x_{0}$ such that $F(x) \cap W \neq \varnothing$ for every $x \in U . F$ is called almost lower semicontinuous (a.l.s.c.) at $x_{0}$ if for each $\varepsilon>0$, there exists a neighborhood $U$ of $x_{0}$ such that
$$
\bigcap_{x \in U} B_{\varepsilon}(F(x)) \neq \varnothing \text {. }
$$
$F$ is called lower semicontinuous (1.s.c.) [resp. almost lower semicontinuous (a.l.s.c.)] if it is l.s.c. (resp. a.l.s.c.) at each point of $X$.

A selection (resp. $\varepsilon$-approximate selection) for $F$ is a function $f: X \rightarrow Y$ such that $f(x) \in F(x)$ (resp. $\left.f(x) \in B_{\varepsilon}(F(x))\right)$ for every $x$ in $X$. Observe that every selection is an $\varepsilon$-approximate selection, but the converse is false in general.

The important and well-known selection theorem of Michael can be stated as follows.
1.1. Theorem (Michael [11]). If $Y$ is complete and $F: X \rightarrow \mathscr{C}(Y)$ is l.s.c., then $F$ has a continuous selection.

While lower semicontinuity of $F$ is sufficient for the existence of a continuous selection, it is in general not necessary. Deutsch and Kenderov have characterized almost lower semicontinuity and in the process showed that it is a necessary condition for the existence of a continuous selection.
1.2. Theorem (Deutsch and Kenderov [5]). Let $F: X \rightarrow \mathscr{C}(Y)$. Then $F$ is a.l.s.c. if and only if for each $\varepsilon>0, F$ has a continuous $\varepsilon$-approximate selection.

In particular, a.l.s.c. is weaker than l.s.c. It was also observed in [5] that, in certain cases, the almost lower semicontinuity of $F$ is equivalent to the existence of a continuous selection for $F$. (This is the case, for example, when $Y$ is one dimensional and $F: X \rightarrow \mathscr{C}(Y)$ has bounded images, or when the set of points in $X$ where $F(x)$ is a singleton is dense in $X$.) This has some interesting ramifications when $F$ is a metric projection.

Recall that the metric projection or nearest-point mapping onto a (finitedimensional) subspace $Y$ of the normed linear space $X$ is the mapping $P_{Y}: X \rightarrow 2^{Y}$ defined by

$$
P_{Y}(x):=\{y \in Y \mid\|x-y\|=d(x, Y)\} .
$$

That is, $P_{Y}(x)$ is the set of all best approximations (= nearest points) in $Y$ to $x$. It is well known that $P_{Y}$ has nonempty, closed, convex, and bounded images so $P_{Y}: X \rightarrow \mathscr{C}(Y)$.

The main results of the paper can now be briefly summarized. Theorem 2.4 characterizes when $F$ has a continuous selection and is a kind of "dual" to a theorem of Michael (see Theorem 2.6) where lower semicontinuity was characterized. A characterization of almost lower semicontinuity by a property which is (formally) stronger than that of Theorem 1.2 is given in Theorem 3.3. Theorem 4.5 is a geometric characterization of those one-dimensional subspaces $Y$ of a normed linear space $X$ such that $P_{Y}$ admits a continuous selection. Using Theorem 4.5, we give in Theorem 5.1 (resp. Theorem 6.3) an intrinsic characterization of those onedimensional subspaces $Y$ in the classical Banach space $C_{0}(T), T$ locally compact (resp. $L_{1}(T, \mathscr{S}, \mu)$ ) such that $P_{Y}$ admits a continuous selection. The former result generalizes a theorem of Lazar, Morris, and Wulbert [10], who proved the particular case when $T$ is compact by a more involved argument. The latter result generalizes a theorem of Lazar [9], who proved the special case of $l_{1}$-space. In contrast to our unified approach, the methods used in [10] are completely different from those used in [9].

## 2. Lower Semicontinuity and Continuous Selections

In this section we study some connections between lower semicontinuity and certain kinds of continuous selections. For ease of reference, we collect some basic known facts about constructing new l.s.c. maps from given ones in the next proposition (see, e.g., [11]).
2.1. Proposition. (1) If $F: X \rightarrow 2^{Y}$ is l.s.c., so are the mappings $\bar{F}, \operatorname{co}(F)$, and $\overline{\mathrm{co}}(F)$. (Here $\vec{F}(x):=\overline{F(x)}$, where the bar denotes closure and $\operatorname{co}(F)(x):=\operatorname{co}(F(x))$, where "co" denotes "convex hull of.")
(2) If $G_{i}: X \rightarrow 2^{Y}$ is l.s.c. for each $i \in I$, then $\bigcup_{i \in I} G_{i}$ is also l.s.c., where $\left(\bigcup_{i \in I} G_{i}\right)(x):=\bigcup_{i \in I} G_{i}(x)$.
(3) Let $F: X \rightarrow 2^{Y}$ be l.s.c., $A$ a nonempty closed set in $X$, and $\alpha: A \rightarrow Y$ a continuous function with $\alpha(x) \in F(x)$ for every $x \in A$. Then the mapping $G$ defined on $X$ by

$$
G(x)= \begin{cases}F(x) & \text { if } \quad x \in X \backslash A \\ \{\alpha(x)\} & \text { if } \quad x \in A\end{cases}
$$

is l.s.c.
2.2. Definition. Let $F, G: X \rightarrow 2^{Y}$. $G$ is called a submap of $F$, denoted $G \subset F$, provided $G(x) \subset F(x)$ for every $x \in X$.

If $\mathscr{S}$ is a collection of submaps of $F$, a mapping $G_{0} \in \mathscr{S}$ is called a maximal submap for $\mathscr{S}$ if $G \in \mathscr{S}$ and $G_{0} \subset G$ implies $G=G_{0}$.
2.3. Lemma. If $F: X \rightarrow \mathscr{C}(Y)$ has a maximal l.s.c. submap, it is unique.

Proof. Let $G_{1}$ and $G_{2}$ both be maximal I.s.c. submaps of $F$. Then the $\operatorname{map} G=G_{1} \cup G_{2}$ is 1.s.c. by $2.1(2)$ and the map $\overline{c o}(G)$ is 1.s.c. by 2.1(1). But $G_{i} \subset \overline{\mathrm{co}}(G) \subset F$ for $i=1,2$. Since $G_{i}$ is maximal for $i=1,2$, it follows that $\overline{\operatorname{co}}(G)=G_{i}$ for $i=1,2$ and hence $G_{1}=G_{2}$.

The next result shows that while l.s.c. is not necessary to guarantee a continuous selection, some submap must be 1.s.c.!
2.4. Theorem. Let $Y$ be complete and $F: X \rightarrow \mathscr{C}(Y)$. Then the following statements are equivalent.
(1) F has a continuous selection;
(2) F has "local" continuous selections, i.e., for each $x_{0} \in X$, there is a neighborhod $U\left(x_{0}\right)$ of $x_{0}$ and a continuous function $f_{x_{0}}: U\left(x_{0}\right) \rightarrow Y$ such that $f_{x_{0}}(x) \in F(x)$ for every $x \in U\left(x_{0}\right)$
(3) $F$ gas a (unique) maximal l.s.c. submap
(4) F has a l.s.c. submap.

Proof. (1) $\Rightarrow$ (2). This is obvious since the restriction of a continuous selection $f$ to any neighborhood $U\left(x_{0}\right)$ of $x_{0}$ can be chosen for $f_{x_{0}}$.
(2) $\Rightarrow$ (1). Suppose (2) holds. Since $X$ is paracompact, the open cover $\left\{U\left(x_{0}\right) \mid x_{0} \in X\right\}$ of $X$ has a locally finite refinement $\left\{V_{i} \mid i \in I\right\}$. For each $i \in I$, choose $x_{i} \in X$ so that $V_{i} \subset U\left(x_{i}\right)$. Using paracompactness, we can choose a partition of unity $\left\{p_{i} \mid i \in I\right\}$ subordinate to $\left\{V_{i} \mid i \in I\right\}$. That is, each function $p_{i}: X \rightarrow[0,1]$ is continuous, $p_{i}=0$ off $V_{i}$, and $\sum_{i \in I} p_{i}(x)=1$ for all $x \in X$. Define $f$ on $X$ by

$$
f(x)=\sum_{i \in I} p_{i}(x) f_{x_{i}}(x), \quad x \in X,
$$

Given any $x \in X$, there is a neighborhood of $x$ which intersects only finitely many of the $V_{i}$ so $x \in V_{i}$ for only a finite set of indices $I(x)$ in $I$. Thus $f$ is well-defined, continuous, and has range in $Y$. Further,

$$
f(x)=\sum_{i \in H(x)} p_{i}(x) f_{x_{i}}(x) \in \operatorname{co}(F(x))=F(x)
$$

so $f$ is a continuous selection for $F$.
$(1) \Rightarrow(3)$. Assume $F$ has a continuous selection $f$ and let $\mathscr{L}$ denote the collection of all 1.s.c. submaps of $F . \mathscr{L} \neq \varnothing$ since $f \in \mathscr{L}$. Define
$G_{0}=\bigcup\{G \mid G \in \mathscr{L}\}$. By Proposition 2.1(2), $G_{0}$ is 1.s.c. Further, the map $H=\overline{\mathrm{co}}\left(G_{0}\right)$ is l.s.c. by $2.1(1)$. Also, $G \subset H$ for every $G \in \mathscr{L}$. That is, $H$ is a maximal l.s.c. submap for $\mathscr{L}$. By Lemma 2.3, $H$ is unique.
(3) $\Rightarrow$ (4). Obvious.
$(4) \Rightarrow(1)$. Suppose $G$ is a 1.s.c. submap of $F$. Then $G_{0}:=\overline{\operatorname{co}}(G)$ is a 1.s.c. submap also. By Michael's selection theorem 1.1, $G_{0}$ has a continuous selection which is obviously also a continuous selection for $F$. 【

One can give an explicit formula for the maximal l.s.c. submap.
2.5. Proposition. Suppose $F: X \rightarrow \mathscr{C}(Y)$ has a continuous selection. Define a mapping $F^{*}$ on $X$ by

$$
\begin{equation*}
F^{*}(x):=\{y \in F(x) \mid \text { there is a continuous selection } f \text { for } F \text { with } f(x)=y\} . \tag{2.5.1}
\end{equation*}
$$

That is,

$$
F^{*}=\bigcup\{f \mid f \text { is a continuous selection for } F\} .
$$

Then $F^{*}$ is the unique maximal l.s.c. submap of $F$. In particular, $F^{*}: X \rightarrow \mathscr{C}(Y)$.

Proof. Clearly $F^{*}$ is l.s.c. by Proposition 2.1(2), and $F^{*}$ is a submap of $F$. If $F^{*}$ were not maximal, there would exist a 1.s.c. submap $F_{0}$ of $F$ with $F^{*} \subset F_{0}$ and $F^{*} \neq F_{0}$. By replacing $F_{0}$ with $\overline{c o}\left(F_{0}\right)$, we may assume that $F_{0}$ has closed convex images. Then there is an $x_{0} \in X$ with $F_{0}\left(x_{0}\right) \backslash F^{*}\left(x_{0}\right) \neq \varnothing$. Choose $y_{0} \in F_{0}\left(x_{0}\right) \backslash F^{*}\left(x_{0}\right)$ and define $H$ on $X$ by

$$
H(x)=\left\{\begin{array}{lll}
F_{0}(x) & \text { if } & x \neq x_{0} \\
\left\{y_{0}\right\} & \text { if } & x=x_{0} .
\end{array}\right.
$$

By $2.1(3), H: X \rightarrow \mathscr{C}(Y)$ is I.s.c. so, by Theorem 1.1, $H$ has a continuous selection $f: X \rightarrow Y$. Since $H$ is a submap of $F, f$ is also a continuous selection for $F$ with $f\left(x_{0}\right)=y_{0}$. Hence $y_{0} \in F^{*}\left(x_{0}\right)$, a contradiction. Thus $F^{*}$ is maximal and the proof is complete.

Theorem 2.4 equates the existence of a continuous selection for $F$ with the existence of a lower semicontinuous submap of $F$. There is an interesting "dual" result to this which equates the lower semicontinuity of $F$ with the existence of extensions of continuous selections for certain restrictions of $F$. It is essentially due to Michael and can be stated as follows.
2.6. Theorem (Michael [11]). Let $Y$ be complete and $F: X \rightarrow \mathscr{C}(Y)$. Then the following statements are equivalent.
(1) $F$ is l.s.c.;
(2) For each closed subset $A$ of $X$, each continuous selection for $\left.F\right|_{A}$ has an extension to a continuous selection for $F$;
(3) For each $x_{0} \in X$ and $y_{0} \in F\left(x_{0}\right)$, there exists a continuous selection ffor $F$ with $f\left(x_{0}\right)=y_{0}$, i.e., $F=F^{*}$.
[Actually, Michael verified the implications $(1) \Leftrightarrow(2)$ and $(3) \Rightarrow(1)$ in [11]. To verify $(2) \Rightarrow(3)$, let $A=\left\{x_{0}\right\}, f\left(x_{0}\right)=y_{0}$, and observe that $f$ is (trivially) a continuous selection for $\left.F\right|_{A}$. Thus it has an extension to a continuous selection for $F$.]

It follows that if $F$ is l.s.c. and there is some point $x_{0}$ where $F\left(x_{0}\right)$ is not a singleton, the $F$ can not have a unique continuous selection. More precisely, we have the next corollary.
2.7. Corollary. Assume $Y$ is complete, $F: X \rightarrow \mathscr{C}(Y)$ is l.s.c., and $F\left(x_{0}\right)$ is not a singleton for some $x_{0} \in X$. Then $F$ has at least $\operatorname{card}\left(F\left(x_{0}\right)\right)$ distinct continuous selections.

Proof. By Theorem 2.6, for each $y_{0} \in F\left(x_{0}\right), F$ has a continuous selection $f$ with $f\left(x_{0}\right)=y_{0}$. There are obviously at least $\operatorname{card}\left(F\left(x_{0}\right)\right)$ such selections.

For certain mappings (which include metric projections onto subspaces), it is possible to characterize lower semicontinuity in terms of the existence of a continuous selection having an additional property.
2.8. Theorem. Let $Y$ be a complete subspace of the normed linear space $X$ and $F: X \rightarrow \mathscr{C}(Y)$. Assume that

$$
\operatorname{ker} F:=\{x \in X \mid 0 \in F(x)\}
$$

is closed and $F$ is "additive modulo $Y$," i.e., for each $x \in X$ and $y \in Y$,

$$
\begin{equation*}
F(x+y)=F(x)+y . \tag{2.8.1}
\end{equation*}
$$

Then $F$ is l.s.c. if and only if $F$ has a continuous selection $f$ which is "kernelpreserving," i.e., $f(x)=0$ for every $x \in \operatorname{ker} F$.

Proof. Suppose $F$ is l.s.c. Then the restriction mapping $\left.F\right|_{\text {ker } F}$ has a continuous selection (viz. $g=0$ ). By Theorem 2.6, $F$ has a continuous selection $f$ which is an extension of $g$. Thus $f$ is kernel-preserving.

Conversely, suppose $F$ has a continuous selection which is kernel-preserving. Let $x_{0} \in X$ and let $W$ be an open set in $Y$ with $F\left(x_{0}\right) \cap W \neq \varnothing$. We will show that there is a neighborhood $U$ of $x_{0}$ such that $F(x) \cap W \neq \varnothing$ for all $x \in U$. Let $y_{0} \in F\left(x_{0}\right) \cap W$. Then there is an $\varepsilon>0$ such that $B_{\varepsilon}\left(y_{0}\right) \subset W$. Now $0 \in F\left(x_{0}\right)-y_{0}=F\left(x_{0}-y_{0}\right)$ so $f\left(x_{0}-y_{0}\right)=0$. Choose a neighborhood $U_{0}$ of $z_{0}:=x_{0}-y_{0}$ so that

$$
f(z) \in B_{\varepsilon}\left(f\left(z_{0}\right)\right)=B_{\varepsilon}(0)
$$

for every $z \in U_{0}$. Then $U:=U_{0}+y_{0}$ is a neighborhood of $x_{0}$ and for each $x \in U, x=z+y_{0}$ for some $z \in U_{0}$. Thus

$$
\begin{aligned}
f(z) & +y_{0} \in\left[F(z)+y_{0}\right] \cap\left[B_{\varepsilon}(0)+y_{0}\right] \\
& =F\left(z+y_{0}\right) \cap B_{\varepsilon}\left(y_{0}\right)=F(x) \cap B_{\varepsilon}\left(y_{0}\right) \subset F(x) \cap W
\end{aligned}
$$

implies that $F(x) \cap W \neq \varnothing$ for every $x \in U$. This proves that $F$ is l.s.c. at $x_{0}$. Since $x_{0}$ was arbitrary, $F$ is l.s.c.

Recall that a subspace $Y$ of the normed linear space $X$ is called proximinal if

$$
P_{Y}(x):=\{y \in Y \mid\|x-y\|=d(x, Y)\}
$$

is nonempty for every $x \in X$. For example, any finite-dimensional subspace is proximinal. It is well known and easy to prove that $P_{Y}$ is additive modulo $Y$ and

$$
\text { ker } P_{Y}:=\left\{x \in X \mid 0 \in P_{Y}(x)\right\}=\{x \in X \mid\|x\|=d(x, Y)\}
$$

is closed. Thus, as consequence of Theorem 2.8 , we immediately obtain the following result of Krüger.
2.9. Theorem (Krüger [8]). Let $Y$ be a complete proximinal subspace of the normed linear space $X$. Then $P_{Y}$ is l.s.c. if and only if $P_{Y}$ has a continuous selection $f$ with $f(x)=0$ for every $x \in \operatorname{ker} P_{Y}$.

Remarks. (1) The proof of Theorem 2.8 is an obvious generalization of Krüger's original proof for the special case of metric projections. (His proof also used Proposition 2.1(3).)
(2) There are mappings which are not metric projections but which satisfy the hypothesis of Theorem 2.8. For example, $F(x):=P_{Y}(x)+f(x)$, where $f: X \rightarrow Y$ is any continuous function satisfying $f(x+y)=f(x)$ for every $x \in X$ and $y \in Y$.

## 3. Almost Lower Semicontinuity and Continuous Selections

The distinction between lower semicontinuity and almost lower semicontinuity is further elucidated in the next lemma.
3.1. Lemma. Let $F: X \rightarrow 2^{Y}, x_{0} \in X$, and consider the following statements.
(1) F is l.s.c. at $x_{0}$ :
(2) For each $y_{0} \in F\left(x_{0}\right)$ and $\varepsilon>0$, there exists a neighborhood $U$ of $x_{0}$ such that

$$
\begin{equation*}
y_{0} \in \bigcap_{x \in U} B_{\varepsilon}(F(x)) ; \tag{3.1.1}
\end{equation*}
$$

(3) For each $y_{0} \in F\left(x_{0}\right)$ and each net $x_{n} \rightarrow x_{0}$,

$$
\begin{equation*}
d\left(y_{0}, F\left(x_{n}\right)\right) \rightarrow 0 ; \tag{3.1.2}
\end{equation*}
$$

(4) There exists $y_{0} \in F\left(x_{0}\right)$ such that for each net $x_{n} \rightarrow x_{0}$, $d\left(y_{0}, F\left(x_{n}\right)\right) \rightarrow 0$;
(5) There exists $y_{0} \in F\left(x_{0}\right)$ such that for each $\varepsilon>0$, there exists a neighborhood $U$ of $x_{0}$ with

$$
y_{0} \in \bigcap_{x \in U} B_{\varepsilon}(F(x)) ;
$$

(6) For each $\varepsilon>0$, there exists a neighborhood $U$ of $x_{0}$ such that

$$
\begin{equation*}
F\left(x_{0}\right) \cap\left[\bigcap_{x \in U} B_{\varepsilon}(F(x))\right] \neq \varnothing ; \tag{3.1.3}
\end{equation*}
$$

(7) $F$ is a.l.s.c. at $x_{0}$.

Then

$$
(1) \Leftrightarrow(2) \Leftrightarrow(3) \Rightarrow(4) \Leftrightarrow(5) \Rightarrow(6) \Leftrightarrow(7) .
$$

Moreover, if $F\left(x_{0}\right)$ is compact, then $(6) \Rightarrow(5)$ and the last four statements are equivalent. If $F\left(x_{0}\right)$ is a singleton, then all seven statements are equivalent. If $X$ is a metric space, then "net" may be replaced by "sequence" in (3) and (4).

Proof. The equivalence of the first three statements is well known and goes back at least to Hahn [7].

The implication $(3) \Rightarrow(4)$ is obvious.
$(4) \Rightarrow(5)$. Suppose (5) fails. Then for each $y_{0} \in F\left(x_{0}\right)$ there exists an $\varepsilon>0$ such that for each neighborhood $U$ of $x_{0}$, there is an $x_{U} \in U$ with $y_{0} \notin B_{\varepsilon}\left(F\left(x_{U}\right)\right)$, i.e., $d\left(y_{0}, F\left(x_{U}\right)\right) \geqslant \varepsilon$. Then the net $\left\{x_{U}\right\}$ converges to $x_{0}$ but (3.1.2) fails. Thus (4) fails.
$(5) \Rightarrow(4)$. Assume (5) holds and let $\left\{x_{n}\right\}$ be a net converging to $x_{0}$. For any $\varepsilon>0$, choose a neighborhood $U$ of $x_{0}$ so that (3.1.1) holds. Then $x_{n} \in U$ eventually so $y_{0} \in B_{\varepsilon}\left(F\left(x_{n}\right)\right)$ eventually, i.e., $d\left(y_{0}, F\left(x_{n}\right)\right)<\varepsilon$ eventually. Thus (3.1.2) holds.

The implications $(5) \Rightarrow(6)$ and $(6) \Rightarrow(7)$ are obvious.
$(7) \Rightarrow(6)$. Suppose $F$ is a.l.s.c. at $x_{0}$ and let $\varepsilon>0$. Then there is a neighborhood $U$ of $x_{0}$ such that

$$
\bigcap_{x \in U} B_{\varepsilon / 2}(F(x)) \neq \varnothing
$$

Select any $y \in \bigcap_{x \in U} B_{\varepsilon / 2}(F(x))$. For each $x \in U$, choose $y_{x} \in F(x)$ such that $\left\|y-y_{x}\right\|<\varepsilon / 2$. It follows that

$$
\left\|y_{x_{0}}-y_{x}\right\| \leqslant\left\|y_{x_{0}}-y\right\|+\left\|y-y_{x}\right\|<\varepsilon
$$

for each $x \in U$. Hence $y_{x_{0}} \in \bigcap_{x \in U} B_{\varepsilon}(F(x))$ and so (3.1.3) holds. This verifies (6).

Now assume $F\left(x_{0}\right)$ is compact and (6) holds. We will show that (5) holds. For each integer $n$, there is a neighborhood $U_{n}$ of $x_{0}$ such that

$$
A_{n}:=F\left(x_{0}\right) \cap\left[\bigcap_{x \in U_{n}} B_{1 / n}(F(x))\right] \neq \varnothing
$$

Select any $y_{n} \in A_{n}$. By compactness of $F\left(x_{0}\right)$, the sequence $\left\{y_{n}\right\}$ has a cluster point $y_{0} \in F\left(x_{0}\right)$. Now let $\left\{x_{\alpha}\right\}$ be a net in $X$ with $x_{\alpha} \rightarrow x_{0}$. Then for each $n, x_{\alpha} \in U_{n}$ eventually. Hence $y_{n} \in B_{1 / n}\left(F\left(x_{\alpha}\right)\right)$ for $\alpha$ eventually so

$$
\begin{aligned}
d\left(y_{0}, F\left(x_{\alpha}\right)\right) & \leqslant d\left(y_{0}, y_{n}\right)+d\left(y_{n}, F\left(x_{\alpha}\right)\right) \\
& \leqslant d\left(y_{0}, y_{n}\right)+1 / n
\end{aligned}
$$

Since $y_{0}$ is a cluster point of $\left\{y_{n}\right\}$, for each $\varepsilon>0$ and integer $n$ with $n>2 / \varepsilon$, there is an $n_{0} \geqslant n$ such that $d\left(y_{0}, y_{n_{0}}\right)<\varepsilon / 2$. Hence $d\left(y_{0}, F\left(x_{\alpha}\right)\right)<\varepsilon$ eventually. This verifies (5).

The remainder of the proof is easy.
An example given at the end of [5] shows that the implication (4) $\Rightarrow$ (3) is false, even when $F\left(x_{0}\right)$ is compact and $F$ is a metric projection
onto a one-dimensional subspace. Also, P. Kenderov has communicated an example to us showing that the implication $(6) \Rightarrow(5)$ is false when $F\left(x_{0}\right)$ is not compact.
3.2. Definition. A subset $I$ of $X$ is called discrete if $\Pi\{x\}$ is closed for each $x \in I$. Equivalently, $I$ is discrete iff $I$ has no accumulation points iff $I$ is closed and, for each $x \in I$, there exists a neighborhood $U$ of $x$ such that $U \cap I=\{x\}$.
Note that each discrete set is necessarily closed, and every finite set is discrete. The next result is a strengthening of Theorem 1.2.
3.3. Theorem. Let $F: X \rightarrow \mathscr{C}(Y)$. Then the following statements are equivalent.
(1) $F$ is a.l.s.c.;
(2) For each $x_{0} \in X$ and $\varepsilon>0$, there is a continuous $\varepsilon$-approximate selection $f$ for $F$ with $f\left(x_{0}\right) \in F\left(x_{0}\right)$;,
(3) For each discrete set $I$ in $X$ and $\varepsilon>0$, there exists a continuous $\varepsilon$-approximate selection for $F$ with $f(x) \in F(x)$ for all $x \in I$.

Proof. (1) $\Rightarrow(2)$. Assume $F$ is a.l.s.c. and fix any $x_{0} \in X$. By Theorem 1.2, for every $\varepsilon>0$, there exists a continuous $\varepsilon / 2$-approximate selection $f_{1}$ for $F$. Choose any $y_{0} \in F\left(x_{0}\right)$ with $f_{1}\left(x_{0}\right) \in B_{\varepsilon / 2}\left(y_{0}\right)$. Define $f$ on $X$ by

$$
f(x)=f_{1}(x)+y_{0}-f_{1}\left(x_{0}\right) .
$$

Then $f$ is continuous,

$$
f(x) \in B_{\varepsilon / 2}(F(x))+B_{\varepsilon / 2}(0) \subset B_{\varepsilon}(F(x))
$$

for every $x \in X$, and $f\left(x_{0}\right)=y_{0} \in F\left(x_{0}\right)$. Thus $f$ is a continuous $\varepsilon$-approximate selection for $F$ with $f\left(x_{0}\right) \in F\left(x_{0}\right)$. This proves (2).
(2) $\Rightarrow$ (3). Assume (2) holds, let $I$ be a discrete set in $X$, and $\varepsilon>0$. Then for each $x \in I$, there exists a continuous $\varepsilon$-approximate selection $f_{x}$ for $F$ such that $f_{x}(x) \in F(x)$. Define

$$
U(x):=X \backslash(I \backslash\{x\})=(X \backslash I) \cup\{x\} .
$$

Then $\{U(x) \mid x \in I\}$ is an open cover of $X$. Let $\left\{V_{j} \mid j \in J\right\}$ be a locally finite refinement of $\{U(x) \mid x \in I\}$. For each $j \in J$, choose $x_{j} \in I$ so that $V_{j} \subset U\left(x_{j}\right)$. Choose a partition of unity $\left\{p_{j} \mid j \in J\right\}$ subordinate to the cover $\left\{V_{j} \mid j \in J\right\}$. Then each $p_{j}$ is continuous, $0 \leqslant p_{j} \leqslant 1, p_{j}=0$ off $V_{j}$, and $\sum_{j \in J} p_{j}(x)=1$ for
every $x \in X$. In particular, $p_{j}(x)=0$ for all $x \notin U\left(x_{j}\right)$ so $p_{j}(x)=0$ for all $x \in I \backslash\left\{x_{j}\right\}$ and hence $p_{j}\left(x_{j}\right)=1$. Define $f$ on $X$ by

$$
f(x)=\sum_{j \in J} p_{j}(x) f_{x_{j}}(x), \quad x \in X
$$

Then $f$ is continuous,

$$
f(x) \in \operatorname{co}\left\{f_{x_{j}}(x) \mid j \in J\right\} \subset \operatorname{co}\left(B_{\varepsilon}(F(x))\right)=B_{\varepsilon}(F(x))
$$

for all $x \in X$, and, if $x \in I, f(x)=f_{x}(x) \in F(x)$. Thus $f$ is a continuous $\varepsilon$-approximate selection for $F$ such that $f(x) \in F(x)$ for every $x \in I$. This proves (3).

The implication $(3) \Rightarrow(1)$ follows by Theorem 1.2.

## 4. Continuous Selections for Metric Projections onto One-Dimensional Subspaces

In this section we will be exclusively connerned with the metric projection onto a one-dimensional subspace. A geometric characterization of when such a metric projection admits a continuous selection is obtained. In the last two sections, this result will be used to obtain intrinsic characterizations of the one-dimensional subspaces in $C_{0}(T)$ and $L_{1}(\mu)$ whose metric projections admit continuous selections.

Let $X$ be a normed linear space, $y_{1} \in X \backslash\{0\}$, and let $\left[y_{1}\right]$ denote the one-dimensional subspace spanned by $y_{1}$ :

$$
\left[y_{1}\right]:=\left\{\alpha y_{1} \mid \alpha \in \mathbf{R}\right\} .
$$

The following result of [5] is central to our development. It essentially states that a rather weak continuity property of $P_{[y]}$ is equivalent to the existence of a continuous selection.
4.1. Theorem [5]. The following statements are equivalent.
(1) $P_{\left[y_{1]}\right]}$ has a continuous selection;
(2) $P_{[y]]}$ is a.l.s.c.;
(3) $P_{[y, 1]}$ is 2-l.s.c.

Recall [5] that $P_{[y 1]}$ is 2-l.s.c. at $x_{0} \in X$ if, for each $\varepsilon>0$, there exists a neighborhood $U$ of $x_{0}$ such that

$$
\begin{equation*}
B_{\varepsilon}\left(P_{\left[y_{1}\right]}\left(x_{1}\right)\right) \cap B_{\varepsilon}\left(P_{\left[y_{1}\right]}\left(x_{2}\right)\right) \neq \varnothing \tag{4.1.1}
\end{equation*}
$$

whenever $x_{1}, x_{2} \in U$.

If $I$ is any (bounded or unbounded) closed interval in $\mathbf{R}$, we define

$$
I y_{1}:=\left\{\alpha y_{1} \mid \alpha \in I\right\} .
$$

In particular, $\mathbf{R} y_{1}=(-\infty, \infty) y_{1}$ is what we earlier denoted by [ $y_{1}$ ]. It is well known that for every $x \in X$,

$$
P_{[y]]}(x)=I_{x} y_{1}
$$

for some compact interval $I_{x}$ depending on $x$.
Fix any $x \in X$. It is not hard, using the convexity of the function $f(\alpha)=$ $\left\|x+\alpha y_{1}\right\|, \alpha \in \mathbf{R}$, to verify that

$$
\begin{equation*}
P_{\left[y_{1}\right]}(x) \supset[-1,1] y_{1} \tag{4.1.2}
\end{equation*}
$$

holds if and only if

$$
\begin{equation*}
\|x\|=\left\|x+y_{1}\right\|=\left\|x-y_{1}\right\| . \tag{4.1.3}
\end{equation*}
$$

It will be convenient to single out those $x \in X$ which have either of the equivalent properties (4.1.2) or (4.1.3). Define

$$
\begin{align*}
P_{\left[y_{1}\right]}^{0} & :=\left\{x \in X \mid P_{\left[y_{1}\right]}(x) \supset[-1,1] y_{1}\right\} \\
& =\left\{x \in X \mid\|x\|=\left\|x+y_{1}\right\|=\left\|x-y_{1}\right\|\right\} . \tag{4.1.4}
\end{align*}
$$

4.2. Lemma. The following statements are equivalent.
(1) $P_{[y 1]}$ is 2-l.s.c.;
(2) $P_{\left[y_{1}\right]}$ is 2-l.s.c. on $\operatorname{ker} P_{\left[y_{1}\right]}$;
(3) $P_{[y]]}$ is 2-l.s.s. on $P_{[y 1]}^{0}$.

Proof. Since $P_{\left[y_{1}\right]}^{0} \subset \operatorname{ket} P_{\left[y_{1}\right]}$, the implications $(1) \Rightarrow(2) \Rightarrow(3)$ are obvious.
(3) $\Rightarrow$ (1). Suppose $P=P_{\left[y_{1}\right]}$ fails to be 2 -l.s.c. at some $x_{0} \in X$. Then there exist $\varepsilon>0$ and sequences $x_{n} \rightarrow x_{0}$ and $x_{n}^{\prime} \rightarrow x_{0}$ with

$$
B_{\varepsilon}\left(P\left(x_{n}\right)\right) \cap B_{\varepsilon}\left(P\left(x_{n}^{\prime}\right)\right)=\varnothing
$$

for all $n$. Now $P\left(x_{0}\right)=\left[\alpha_{0}, \beta_{0}\right] y_{1}$ for some $\beta_{0}>\alpha_{0}$. Set $y_{0}=\frac{1}{2}\left(\alpha_{0}+\beta_{0}\right) y_{1}$ and $\delta=\frac{1}{2}\left(\beta_{0}-\alpha_{0}\right)$. If $\delta \geqslant 1$, let $z_{0}=x_{0}-y_{0}, z_{n}=x_{n}-y_{0}$, and $z_{n}^{\prime}=x_{n}^{\prime}-y_{0}$. Then $z_{n} \rightarrow z_{0}, z_{n}^{\prime} \rightarrow z_{0}$, and

$$
\begin{aligned}
B_{\varepsilon}\left(P\left(z_{n}\right)\right) \cap B_{\varepsilon}\left(P\left(z_{n}^{\prime}\right)\right) & =B_{\varepsilon}\left(P\left(x_{n}\right)-y_{0}\right) \cap B_{\varepsilon}\left(P\left(x_{n}^{\prime}\right)-y_{0}\right) \\
& =B_{\varepsilon}\left(P\left(x_{n}\right)\right) \cap B_{\varepsilon}\left(P\left(x_{n}^{\prime}\right)\right)-y_{0}=\varnothing
\end{aligned}
$$

for all $n$. Also,

$$
\begin{aligned}
P\left(z_{0}\right) & =P\left(x_{0}\right)-y_{0}=\left[\alpha_{0}, \beta_{0}\right] y_{1}-\frac{1}{2}\left(\alpha_{0}+\beta_{0}\right) y_{1} \\
& =[-\delta, \delta] y_{1} \supset[-1,1] y_{1} .
\end{aligned}
$$

If $0<\delta<1$, let $z_{0}=(1 / \delta)\left(x_{0}-y_{0}\right), \quad z_{n}=(1 / \delta)\left(x_{n}-y_{0}\right), \quad$ and $\quad z_{n}^{\prime}=$ $(1 / \delta)\left(x_{n}^{\prime}-y_{0}\right)$. Then $z_{n} \rightarrow z_{0}, z_{n}^{\prime} \rightarrow z_{0}$, and

$$
\begin{aligned}
B_{\varepsilon}\left(P\left(z_{n}\right)\right) \cap B_{\varepsilon}\left(P\left(z_{n}^{\prime}\right)\right) & =B_{\varepsilon}\left[\frac{1}{\delta} P\left(x_{n}\right)-\frac{1}{\delta} y_{0}\right] \cap B_{\varepsilon}\left[\frac{1}{\delta} P\left(x_{n}^{\prime}\right)-\frac{1}{\delta} y_{0}\right] \\
& =\frac{1}{\delta}\left[B_{\delta \varepsilon}\left(P\left(x_{n}\right)\right) \cap B_{\delta \varepsilon}\left(P\left(x_{n}^{\prime}\right)\right)\right]-\frac{1}{\delta} y_{0} \\
& \subset \frac{1}{\delta}\left[B_{\varepsilon}\left(P\left(x_{n}\right)\right) \cap B_{\varepsilon}\left(P\left(x_{n}^{\prime}\right)\right)\right]-\frac{1}{\delta} y_{0} \\
& =\varnothing
\end{aligned}
$$

for all n. Also,

$$
\begin{aligned}
P\left(z_{0}\right) & =\frac{1}{\delta} P\left(x_{0}\right)-\frac{1}{\delta} y_{0}=\frac{1}{\delta}\left[\alpha_{0}, \beta_{0}\right] y_{1}-\frac{1}{2 \delta}\left(\alpha_{0}+\beta_{0}\right) y_{1} \\
& =\frac{1}{\delta}[-\delta, \delta] y_{1}=[-1,1] y_{1} .
\end{aligned}
$$

In either case, we see that $P$ is not 2-1.s.c. at $z_{0}$ and $z_{0} \in P_{\left[y_{1}\right]}^{0}$. Thus (3) fails.

For a given $x \in X$, the set of peaking functionals for $x$ is the subset of the dual space $X^{*}$ defined by

$$
J(x):=\left\{x^{*} \in X_{1}^{*} \mid x^{*}(x)=\|x\|\right\}
$$

where $X_{1}^{*}:=\left\{x^{*} \in X^{*} \mid\left\|x^{*}\right\| \leqslant 1\right\}$. The annihilator of the subspace $\left[y_{1}\right]$ is the set

$$
y_{1}^{\perp}:=\left\{x^{*} \in X^{*} \mid x^{*}\left(y_{1}\right)=0\right\} .
$$

The extreme points of any set $B$ in the dual space $X^{*}$ will be denoted by ext $B$. Since $J(x)$ is a nonempty weak* compact extremal subset of $X_{1}^{*}$ for any $x$, it follows that $J(x)$ has extreme points and ext $J(x) \subset$ ext $X_{1}^{*}$.
4.3. Lemma. Let $P_{\left[y_{1}\right]}\left(x_{0}\right)=\left[\alpha_{0}, \beta_{0}\right] y_{1}$ with $\alpha_{0} \leqslant \beta_{0}$ and $\alpha \in \mathbf{R}$. Then:
(1) $\alpha<\alpha_{0}$ if and only if

$$
\begin{equation*}
J\left(x_{0}-\alpha y_{1}\right) \subset\left\{x^{*} \in X^{*} \mid x^{*}\left(y_{1}\right)>0\right\} . \tag{4.3.1}
\end{equation*}
$$

(2) $\alpha>\beta_{0}$ if and only if

$$
\begin{equation*}
J\left(x_{0}-\alpha y_{1}\right) \subset\left\{x^{*} \in X^{*} \mid x^{*}\left(y_{1}\right)<0\right\} . \tag{4.3.2}
\end{equation*}
$$

(3) If $\alpha \in\left(\alpha_{0}, \beta_{0}\right)$, then

$$
\begin{equation*}
J\left(x_{0}-\alpha y_{1}\right) \subset\left\{x^{*} \in X^{*} \mid x^{*}\left(y_{1}\right)=0\right\} . \tag{4.3.3}
\end{equation*}
$$

(4) If (4.3.3) holds, then

$$
\begin{equation*}
\alpha \in\left[\alpha_{0} . \beta_{0}\right] . \tag{4.3.4}
\end{equation*}
$$

(5) If $\alpha=\alpha_{0}\left(\right.$ resp. $\left.\alpha=\beta_{0}\right)$ and $\alpha_{0} \neq \beta_{0}$, then

$$
\begin{equation*}
J\left(x_{0}-\alpha y_{1}\right) \subset\left\{x^{*} \in X^{*} \mid x^{*}\left(y_{1}\right) \geqslant 0\right\} \tag{4.3.5}
\end{equation*}
$$

$\left(r e s p . J\left(x_{0}-\alpha y_{1}\right) \subset\left\{x^{*} \in X^{*} \mid x^{*}\left(y_{1}\right) \leqslant 0\right\}\right)$.
Proof. Let $\alpha \in \mathbf{R}$. Then for each $\gamma \in\left[\alpha_{0}, \beta_{0}\right]$ and $x^{*} \in J\left(x_{0}-\alpha y_{1}\right)$, we have

$$
\begin{aligned}
\left\|x_{0}-\alpha y_{1}\right\| & =x^{*}\left(x_{0}-\alpha y_{1}\right)=x^{*}\left(x_{0}-\gamma y_{1}\right)+(\gamma-\alpha) x^{*}\left(y_{1}\right) \\
& \leqslant\left\|x_{0}-\gamma y_{1}\right\|+(\gamma-\alpha) x^{*}\left(y_{1}\right) \\
& =d\left(x_{0},\left[y_{1}\right]\right)+(\gamma-\alpha) x^{*}\left(y_{1}\right) .
\end{aligned}
$$

Hence setting

$$
\delta(\alpha):=\left\|x_{0}-\alpha y_{1}\right\|-d\left(x_{0}\left[y_{1}\right]\right),
$$

we have that

$$
\begin{equation*}
\delta(\alpha) \leqslant(\gamma-\alpha) x^{*}\left(y_{1}\right) \tag{4.3.6}
\end{equation*}
$$

for every $\gamma \in\left[\alpha_{0}, \beta_{0}\right]$ and $x^{*} \in J\left(x_{0}-\alpha y_{1}\right)$.
(1) Assume $\alpha<\alpha_{0}$. Then $\delta(\alpha)>0$ and (4.3.6) implies that $(\gamma-\alpha) x^{*}\left(y_{1}\right)>0$ for all $\gamma \in\left[\alpha_{0}, \beta_{0}\right]$ and $x^{*} \in J\left(x_{0}-\alpha y_{1}\right)$. Hence $x^{*}\left(y_{1}\right)>0$ for all $x^{*} \in J\left(x_{0}-\alpha y_{1}\right)$ and (4.3.1) holds.

Conversely, suppose (4.3.1) holds. We will show that $\alpha<\alpha_{0}$. From (4.3.6) we deduce that $\gamma-\alpha \geqslant 0$ for all $\gamma \in\left[\alpha_{0}, \beta_{0}\right]$. In particular, $\alpha \leqslant \alpha_{0}$. If
$\alpha=\alpha_{0}$, then by the Hahn-Banach theorem, there exists $x^{*} \in J\left(x_{0}-\alpha y_{1}\right) \cap$ $y_{1}^{\perp}$. But this contradicts (4.3.1). Thus $\alpha<\alpha_{0}$.
(2) The proof is similar to (1).
(3) Let $\alpha \in\left(\alpha_{0}, \beta_{0}\right)$. Then by (4.3.6), we see that $(\gamma-\alpha) x^{*}\left(y_{1}\right) \geqslant 0$ for all $x^{*} \in J\left(x_{0}-\alpha y_{1}\right)$ and $\gamma \in\left[\alpha_{0}, \beta_{0}\right]$. It follows that $x^{*}\left(y_{1}\right)=0$ for all $x^{*} \in J\left(x_{0}-\alpha y_{1}\right)$. That is, (4.3.3) holds.
(4) Suppose (4.3.3) holds. From (1) and (2) it follows that $\alpha_{0} \leqslant \alpha \leqslant \beta_{0}$. That is, (4.3.4) holds.
(5) Let $\alpha=\alpha_{0}$ and $\alpha_{0} \neq \beta_{0}$. By (4.3.6), we see that $\left(\gamma-\alpha_{0}\right) x^{*}\left(y_{1}\right) \geqslant 0$ for all $\gamma \in\left[\alpha_{0}, \beta_{0}\right]$ and all $x^{*} \in J\left(x_{0}-\alpha_{0} y_{1}\right)$. In particular, $\left(\beta_{0}-\alpha_{0}\right) x^{*}\left(y_{1}\right) \geqslant 0$ or $x^{*}\left(y_{1}\right) \geqslant 0$ for all $x^{*} \in J\left(x_{0}-\alpha_{0} y_{1}\right)$. This verifies (4.3.6). The case $\alpha=\beta_{0}$ is similar.
4.4. Corollary. Let $P\left(x_{0}\right)=\left[\alpha_{0}, \beta_{0}\right] y_{1}$, with $\alpha_{0} \leqslant \beta_{0}$.
(1) If

$$
\begin{equation*}
J\left(x_{0}-\alpha y_{1}\right) \cap\left\{x^{*} \in X^{*} \mid x^{*}\left(y_{1}\right)>0\right\} \neq \varnothing \tag{4.4.1}
\end{equation*}
$$

then $\alpha \leqslant \alpha_{0}$.
(2) If

$$
\begin{equation*}
J\left(x_{0}-\alpha y_{1}\right) \cap\left\{x^{*} \in X^{*} \mid x^{*}\left(y_{1}\right)<0\right\} \neq \varnothing \tag{4.4.2}
\end{equation*}
$$

then $\alpha \geqslant \beta_{0}$.
Proof. (1) If (4.4.1) holds, then by Lemma 4.3(2) and (3), we see that $\alpha \leqslant \beta_{0}$ and $\alpha \notin\left(\alpha_{0}, \beta_{0}\right)$. Thus $\alpha \leqslant \alpha_{0}$ or $\alpha=\beta_{0}$. If $\alpha_{0}=\beta_{0}$, we're done. If $\alpha_{0} \neq \beta_{0}$ and $\alpha=\beta_{0}$, then by 4.3(5),

$$
J\left(x_{0}-\alpha y_{1}\right) \subset\left\{x^{*} \in X^{*} \mid x^{*}\left(y_{1}\right) \leqslant 0\right\},
$$

which contradicts (4.4.1). Thus, in every case, $\alpha \leqslant \alpha_{0}$.
(2) The proof is similar.

In the product space $X \times X^{*}$, we assume that $X$ has its norm topology and $X^{*}$ its weak* topology. Thus a net $\left\{\left(x_{n}, x_{n}^{*}\right)\right\}$ in $X \times X^{*}$ converges to $\left(x_{0}, x_{0}^{*}\right)$, denoted $\left(x_{n}, x_{n}^{*}\right) \rightarrow\left(x_{0}, x_{0}^{*}\right)$, if and only if $\left\|x_{n}-x_{0}\right\| \rightarrow 0$ and $x_{n}^{*} \rightarrow x_{0}^{*}$ weak ${ }^{*}$, i.e., $x_{n}^{*}(x) \rightarrow x_{0}^{*}(x)$ for every $x \in X$.

For any $x_{0} \in \operatorname{ker} P_{\left[y_{1}\right]}$ and $\sigma \in\{+1,-1\}$, we define a subset of $X^{*}$ as follows.

$$
\begin{aligned}
A\left(x_{0}, \sigma\right):= & y_{1}^{\perp} \cap J\left(x_{0}\right) \cap\left\{x_{0}^{*} \in X_{1}^{*} \mid \text { there is a net }\left\{\left(x_{n}, x_{n}^{*}\right)\right\}\right. \\
& \text { in } X \times X^{*} \text { with }\left(x_{n}, x_{n}^{*}\right) \rightarrow\left(x_{0}, x_{0}^{*}\right), x_{n}^{*} \in \operatorname{ext} J\left(x_{n}+\sigma y_{1}\right), \\
& \text { and } \left.x_{n}^{*}\left(\sigma y_{1}\right)<0 \text { for all } n\right\} .
\end{aligned}
$$

We now state the main result of this section.
4.5. Theorem. The following statements are equivalent.
(1) $P_{\left[y_{1}\right]}$ does not have a continuous selection;
(2) There exist $x_{0} \in \operatorname{ker} P_{\left[y_{1}\right]}$, disjoint compact intervals $I$ and $I^{\prime}$ in $\mathbf{R}$, and sequences $\left\{x_{n}\right\}$ and $\left\{x_{n}^{\prime}\right\}$ converging to $x_{0}$ such that for every $n$,

$$
\begin{equation*}
P_{\left[y_{1}\right]}\left(x_{n}\right) \subset I y_{1}, \quad P_{\left[y_{1}\right]}\left(x_{n}^{\prime}\right) \subset I^{\prime} y_{1} ; \tag{4.5.1}
\end{equation*}
$$

(3) There exists $x_{0} \in X$ with $\left\|x_{0}\right\|=\left\|x_{0}-y_{1}\right\|=\left\|x_{0}+y_{1}\right\|$ such that $A\left(x_{0},+1\right) \neq \varnothing$ and $A\left(x_{0},-1\right) \neq \varnothing$.

Proof. Let $P=P_{\left[y_{1}\right]}$.
$(1) \Rightarrow(2)$. If $P$ does not have a continuous selection, then (by Lemmas 4.1 and 4.2) $P$ fails to be 2-l.s.c. at some $x_{0} \in \operatorname{ker} P$ with $P\left(x_{0}\right)=$ [ $\left.\alpha_{0}, \beta_{0}\right] y_{1}$ and $\alpha_{0}<\beta_{0}$. Thus there exist sequences $\left\{x_{n}\right\}$ and $\left\{x_{n}^{\prime}\right\}$ both converging to $x_{0}$ such that

$$
B_{\varepsilon}\left(P\left(x_{n}\right)\right) \cap B_{\varepsilon}\left(P\left(x_{n}^{\prime}\right)\right)=\varnothing \quad \text { for all } n
$$

Letting $P\left(x_{n}\right)=I_{n} y_{1}$ and $P\left(x_{n}^{\prime}\right)=I_{n}^{\prime} y_{1}$ for some compact intervals $I_{n}$ and $I_{n}^{\prime}$ in $\mathbf{R}$, it follows that

$$
\begin{equation*}
B_{\varepsilon}\left(I_{n} y_{1}\right) \cap B_{\varepsilon}\left(I_{n}^{\prime} y_{1}\right)=\varnothing \quad \text { for all } n \tag{4.5.2}
\end{equation*}
$$

We may assume $\sup I_{n}<\inf I_{n}^{\prime}$ for all $n$; in fact, by (4.5.2) we have (assuming, as we may, that $\left\|y_{1}\right\|=1$ ) that

$$
\begin{equation*}
\sup I_{n}+2 \varepsilon<\inf I_{n}^{\prime} \tag{4.5.3}
\end{equation*}
$$

Since these intervals are uniformly bounded, by passing to a subsequence, we deduce that there exist intervals $J$ and $J^{\prime}$ such that $I_{n} \subset B_{\varepsilon / 2}(J)$, $I_{n}^{\prime} \subset B_{\varepsilon / 2}\left(J^{\prime}\right), J \subset B_{\varepsilon / 2}\left(I_{n}\right)$, and $J^{\prime} \subset B_{\varepsilon / 2}\left(I_{n}^{\prime}\right)$ for all $n$. Using (4.5.3), it follows that

$$
B_{\varepsilon / 2}(J) \cap B_{\varepsilon / 2}\left(J^{\prime}\right) \subset B_{\varepsilon}\left(I_{n}\right) \cap B_{\varepsilon}\left(I_{n}^{\prime}\right)=\varnothing
$$

Thus setting $I=\overline{N_{\varepsilon / 2}(J)}$ and $I^{\prime}=\overline{B_{\varepsilon / 2}\left(J^{\prime}\right)}$, we see that $I$ and $I^{\prime}$ are disjoint compact intervals with $I_{n} \subset I$ and $I_{n}^{\prime} \subset I^{\prime}$ for all $n$. That is, (4.5.1) holds.
(2) $\Rightarrow$ (3). Let $x_{0} \in \operatorname{ker} P, I$ and $I^{\prime}$ be disjoint compact intervals in $\mathbf{R}$, and let $\left\{x_{n}\right\}$ and $\left\{x_{n}^{\prime}\right\}$ be disjoint sequences with $x_{n} \rightarrow x_{0}$ and $x_{n}^{\prime} \rightarrow x_{0}$ such that

$$
P\left(x_{n}\right) \subset I y_{1} \quad \text { and } \quad P\left(x_{n}^{\prime}\right) \subset I^{\prime} y_{1}
$$

for all $n$. By translating $x_{0}, x_{n}$, and $x_{n}^{\prime}$ by an appropriate multiple of $y_{1}$, we may assume that

$$
\sup I<-\delta<\delta<\inf I^{\prime}
$$

for some $\delta>0$. Further, by scaling these same vectors by $\delta^{-1}$, we may also assume that

$$
\begin{equation*}
\sup I<-1<1<\inf I^{\prime} \tag{4.5.4}
\end{equation*}
$$

Using the well-known upper semicontinuity of $P$, it follows that for each $\varepsilon>0$,

$$
P\left(x_{n}\right) \subset B_{\varepsilon}\left(P\left(x_{0}\right)\right) \quad \text { and } \quad P\left(x_{n}^{\prime}\right) \subset B_{\varepsilon}\left(P\left(x_{0}\right)\right)
$$

for $n$ sufficiently large. Using (4.5.4) we deduce that $P\left(x_{0}\right) \supset[-1,1] y_{1}$ or, from the equivalence of (4.1.2) and (4.1.3),

$$
\begin{equation*}
\left\|x_{0}\right\|=\left\|x_{0}+y_{1}\right\|=\left\|x_{0}-y_{0}\right\| . \tag{4.5.5}
\end{equation*}
$$

Now $P\left(x_{n}\right)=\left[\alpha_{n}, \beta_{n}\right] y_{1}$ for some $\alpha_{n} \leqslant \beta_{n}$ and $\left[\alpha_{n}, \beta_{n}\right] \subset I$ since $P\left(x_{n}\right) \subset I y_{1}$. By (4.5.4), $\quad \beta_{n}<-1$ so by Lemma 4.3(2), $J\left(x_{n}+y_{1}\right) \subset$ $\left\{x^{*} \in X_{1}^{*} \mid x^{*}\left(y_{1}\right)<0\right\}$. Select any $x_{n}^{*} \in \operatorname{ext} J\left(x_{n}+y_{1}\right)$. Then $x_{n}^{*}\left(y_{1}\right)<0$. By the weak* compactness of $X_{1}^{*}$, there is a subnet of $\left\{x_{n}^{*}\right\}$ (which we also denote by $\left\{x_{n}^{*}\right\}$ ) that weak* converges to some $x_{0}^{*} \in X_{1}^{*}$. We will show that $x_{0}^{*} \in y_{1}^{\perp} \cap J\left(x_{0}\right)$. First note that since $x_{n}^{*}\left(y_{1}\right)<0$ for all $n, x_{0}^{*}\left(y_{1}\right) \leqslant 0$. If $x_{0}^{*}\left(y_{1}\right)<0$, then there exists $\delta<0$ such that $x_{n}^{*}\left(y_{1}\right) \leqslant-\delta$ eventually. Hence

$$
\begin{aligned}
\left\|x_{n}+y_{1}\right\| & =x_{n}^{*}\left(x_{n}+y_{1}\right) \leqslant x_{n}^{*}\left(x_{n}\right)-\delta \quad \text { eventually } \\
& \leqslant\left\|x_{n}\right\|-\delta
\end{aligned}
$$

Passing to the limit yields

$$
\left\|x_{0}+y_{1}\right\| \leqslant\left\|x_{0}\right\|-\delta<\left\|x_{0}\right\|
$$

But this contradicts (4.5.5). Thus we must have $x_{0}^{*}\left(y_{1}\right)=0$ or $x_{0}^{*} \in y_{1}^{\perp}$.
Also,

$$
\begin{aligned}
x_{0}^{*}\left(x_{0}\right) & =\left(x_{0}^{*}-x_{n}^{*}\right)\left(x_{0}\right)+x_{n}^{*}\left(x_{0}-x_{n}\right)+x_{n}^{*}\left(x_{n}+y_{1}\right)-x_{n}^{*}\left(y_{1}\right) \\
& =\left(x_{0}^{*}-x_{n}^{*}\right)\left(x_{0}\right)+x_{n}^{*}\left(x_{0}-x_{n}\right)+\left\|x_{n}+y_{1}\right\|-x_{n}^{*}\left(y_{1}\right) \\
& \rightarrow 0+0+\left\|x_{0}+y_{1}\right\|+0=\left\|x_{0}\right\| .
\end{aligned}
$$

That is, $x_{0}^{*} \in J\left(x_{0}\right)$. This proves that $x_{0}^{*} \in y_{1}^{\perp} \cap J\left(x_{0}\right)$ and $\left(x_{n}, x_{n}^{*}\right) \rightarrow$ $\left(x_{0}, x_{0}^{*}\right)$. Thus $A\left(x_{0},+1\right) \neq \varnothing$.

A similar proof (using $P\left(x_{n}^{\prime}\right)$ instead of $P\left(x_{n}\right)$ ) shows that $A\left(x_{0},-1\right) \neq \varnothing$. Thus (3) is verified.
$(3) \Rightarrow(1)$. Assume that there exists $x_{0} \in X$ with $\left\|x_{0}\right\|=\left\|x_{0}-y_{1}\right\|=$ $\left\|x_{0}+y_{1}\right\|$ such that $A\left(x_{0}+1\right) \neq \varnothing$ and $A\left(x_{0},-1\right) \neq \varnothing$. Let $x_{0}^{*} \in A\left(x_{0},+1\right)$. Then $x_{0}^{*} \in y_{1}^{\perp} \cap J\left(x_{0}\right)$ and there exists a net $\left(x_{n}, x_{n}^{*}\right) \in X \times X^{*}$ such that $x_{n} \rightarrow x_{0}, x_{n}^{*} \rightarrow x_{0}^{*}$ weak $^{*}, x_{n}^{*} \in \operatorname{ext} J\left(x_{n}+y_{1}\right)$, and $x_{n}^{*}\left(y_{1}\right)<0$ for all $n$. Then by Corollary 4.4(2), we have that $\beta_{n} \leqslant-1$, where $P\left(x_{n}\right):=\left[\alpha_{n}, \beta_{n}\right] y_{1}$.

Similarly, using the fact that $A\left(x_{0},-1\right) \neq \varnothing$, we deduce from 4.4(1) that there exists a sequence $\left\{x_{n}^{\prime}\right\}$ converging to $x_{0}$ and $1 \leqslant \alpha_{n}^{\prime}$, where $P\left(x_{n}^{\prime}\right):=\left[\alpha_{n}^{\prime}, \beta_{n}^{\prime}\right] y_{1}$. Clearly, $P$ is not 2 -l.s.c. at $x_{0}$. Hence $P$ cannot have a continuous selection by Theorem 4.1.

## 5. One-Dimensional Subspaces in $C_{0}(T)$

Let $T$ be a locally compact Hausdorff space and let $C_{0}(T)$ be the linear space of all continuous real functions $x$ on $T$ which "vanish at infinity," i.e., the set $\{t \in T||x(t)| \geqslant \varepsilon\}$ is compact for each $\varepsilon>0$. Endowed with the supremum norm $\|x\|=\sup \{|x(t)| \mid t \in T\}, C_{0}(T)$ is a Banach space. When $T$ is compact, $C_{0}(T)$ reduces to the Banach space of all continuous real functions on $T$, and is usually denoted by $C(T)$.

The boundary (resp. cardinality) of a subset $Z$ of $T$ is denoted by bd $Z$ (resp. card $Z$ ). The zero set of an element $x \in C_{0}(T)$ is the set $Z(x):=x^{-1}(0)$. We shall say that $x$ does not change sign at $t$ if there is a neighborhood $U$ of $t$ such that either $x \geqslant 0$ on $U$ or $x \leqslant 0$ on $U$.
By the well-known Arens-Kelley theorem [1] (stated for $T$ compact but also valid when $T$ is locally compact; see [3, Lemma 3.3] for this and other generalizations),

$$
\operatorname{ext} C_{0}(T)_{1}^{*}=\left\{\sigma e_{t} \mid \sigma= \pm 1, t \in T\right\}
$$

where $e_{t}$ is defined on $C_{0}(T)$ by

$$
e_{t}(x):=x(t), \quad x \in C_{0}(T) .
$$

Moreover, ext $C_{0}(T)_{1}^{*}$ is weak* closed if $T$ is compact, and when $T$ is not compact, the weak* closure of ext $C_{0}(T)_{1}^{*}$ is the union of ext $C_{0}(T)_{1}^{*}$ and 0 .

The main result of this section is the following intrinsic characterization of those one-dimensional subspaces in $C_{0}(T)$ whose metric projections admit continuous selections. In the particular case when $T$ is compact, it had been established by Lazar, Morris, and Wulbert [10] by a rather lengthy ad hoc argument. Our proof is based on Theorem 4.5 and is relatively short and direct.
5.1. Theorem. Let $y_{1} \in C_{0}(T) \backslash\{0\}$. The following statements are equivalent.
(1) $P_{\left[y_{1}\right]}$ has a continuous selection;
(2) (i) card $\left[\right.$ bd $\left.Z\left(y_{1}\right)\right] \leqslant 1$ and, (ii) for each $t \in \operatorname{bd} Z\left(y_{1}\right), y_{1}$ does not change sign at $t$.

Proof. We may assume $\left\|y_{1}\right\|<1$.
$(1) \Rightarrow(2)$. Supose (2) fails. Then either $\operatorname{card}\left[\operatorname{bd} Z\left(y_{1}\right)\right]>1$ or $\operatorname{bd} Z\left(y_{1}\right)=\left\{t_{0}\right\}$ and $y_{1}$ changes sign at $t_{0}$.

Case 1. card $\left[\operatorname{bd} Z\left(y_{1}\right)\right]>1$.
Choose distinct points $t_{0}$ and $t_{0}^{\prime}$ in $\operatorname{bd} Z\left(y_{1}\right)$. There are four possible locations for these points: either (i) $t_{0}, t_{0}^{\prime} \in \overline{y_{1}^{-1}((0, \infty))}$, (ii) $t_{0} \in \overline{y_{1}^{-1}((0, \infty))}$ and $t_{0}^{\prime} \in \overline{y_{1}^{-1}((-\infty, 0))}$, (iii) $t_{0}, t_{0}^{\prime} \in \overline{y_{1}^{-1}((-\infty, 0))}$, or (iv) $t_{0} \in$ $\overline{y_{1}^{-1}((-\infty, 0))}$ and $t_{0}^{\prime} \in \overline{y_{1}^{-1}((0, \infty))}$. By replacing $y_{1}$ with $-y_{1}$, (iii) is subsumed in (i) and (iv) is subsumed in (ii). Thus we need only consider the possibilities (i) and (ii).

Case 1(i). $\quad t_{0}, t_{0}^{\prime} \in \overline{\left\{t \in T \mid y_{1}(t)>0\right\}}$.
Choose disjoint neighborhoods $U_{0}$ to $t_{0}$ and $U_{0}^{\prime}$ of $t_{0}^{\prime}$. Using Urysohn's lemma, it is possible to choose an $x_{0} \in C_{0}(T)$ such that $0 \geqslant x_{0} \geqslant$ $\left(-1+y_{1}\right) \wedge\left(-1-y_{1}\right)$ on $U_{0}, 0 \leqslant x_{0} \leqslant\left(1+y_{1}\right) \wedge\left(1-y_{1}\right)$ on $U_{0}^{\prime}, x_{0}=0$ off $U_{0} \cup U_{0}^{\prime}, x_{0}\left(t_{0}\right)=-1$, and $x_{0}\left(t_{0}^{\prime}\right)=1$. Then $\left\|x_{0}\right\|=1$. Also, for $t \in U_{0}$,

$$
\begin{aligned}
-1 & \leqslant y_{1}(t) \leqslant y_{1}(t)-x_{0}(t) \leqslant y_{1}(t)-\left[\left(-1+y_{1}(t)\right) \vee\left(-1-y_{1}(t)\right)\right] \\
& =y_{1}(t)+\left(1-y_{1}(t)\right) \wedge\left(1+y_{1}(t)\right) \\
& =1 \wedge\left(1+2 y_{1}(t)\right) \leqslant 1 .
\end{aligned}
$$

For $t \in U_{0}^{\prime}$,

$$
-1 \leqslant-y_{1}(t) \leqslant x_{0}(t)-y_{1}(t) \leqslant 1 \wedge\left(1-2 y_{1}(t)\right) \leqslant 1 .
$$

For $t \notin U_{0} \cup U_{0}^{\prime}$,

$$
\left|x_{0}(t)-y_{1}(t)\right|=\left|y_{1}(t)\right| \leqslant 1 .
$$

Finally, since $\left|x_{0}\left(t_{0}\right)-y_{1}\left(t_{0}\right)\right|=\left|x_{0}\left(t_{0}\right)\right|=1$, it follows that $\left\|x_{0}-y_{1}\right\|=1$. Similarly, $\left\|x_{0}+y_{1}\right\|=1$. Thus $\left\|x_{0}\right\|=\left\|x_{0}-y_{1}\right\|=\left\|x_{0}+y_{1}\right\|$.

Let $\mathscr{U}$ be the collection of all neighborhoods $U$ of $t_{0}$, ordered by inclusion. Then $\cap\{U \mid U \in \mathscr{U}\}=\left\{t_{0}\right\}$ and, for each $U \in \mathscr{U}$, we can choose a point $t_{U} \in U$ such that $y_{1}\left(t_{U}\right)>0$. Then the net $\left\{t_{U}\right\}$ converges to $t_{0}$. By Urysohn's lemma, for each $U \in \mathscr{U}$, there exists a function $g_{U} \in C_{0}(T)$ such that $0 \leqslant g_{U} \leqslant 1, g_{U}=0$ off $U$, and $g_{U}\left(t_{U}\right)=1$. Then the function $x_{U}:=$
$g_{U}\left(-1-x_{0}-y_{1}\right)+x_{0}$ is in $C_{0}(T), x_{U} \leqslant x_{0}$ since $-1-\left(x_{0}+y_{1}\right) \leqslant 0$, and $x_{U}=x_{0}$ off $U$. Given any $\varepsilon>0$, choose a neighborhood $U_{\varepsilon}$ of $t_{0}$ such that $x_{0}(t)<-1+\varepsilon / 2$ and $y_{1}(t)<\varepsilon / 2$ for $t \in U_{\varepsilon}$. Thus for every $U \in \mathscr{U}$ with $U \subset U_{\varepsilon}$, and for all $t \in U$, we see that

$$
\left|x_{v}(t)-x_{0}(t)\right| \leqslant y_{1}(t)+x_{0}(t)+1<\varepsilon .
$$

Hence $\left\|x_{U}-x_{0}\right\|<\varepsilon$ so the net $\left\{x_{U}\right\}$ converges to $x_{0}$. Further, for every $t \in T$,

$$
\begin{aligned}
\left|x_{U}(t)+y_{1}(t)\right| & =\left|g_{U}(t)(-1)+\left[1-g_{U}(t)\right]\left\{x_{0}(t)+y_{1}(t)\right\}\right| \\
& \leqslant g_{U}(t)+\left[1-g_{U}(t)\right]\left\|x_{0}+y_{1}\right\|=1
\end{aligned}
$$

since $\left\|x_{0}+y_{1}\right\|=1$. Since

$$
x_{U}\left(t_{U}\right)+y_{1}\left(t_{U}\right)=-g_{U}\left(t_{U}\right)=-1
$$

it follows that $\left\|x_{U}+y_{1}\right\|=1$ and

$$
-\left[x_{U}\left(t_{U}\right)+y_{1}\left(t_{U}\right)\right]=\left\|x_{U}+y_{1}\right\|
$$

Setting $x_{U}^{*}=-e_{t_{U}}$, we see that $x_{U}^{*} \in \operatorname{ext} J\left(x_{U}+y_{1}\right), x_{U}^{*}\left(y_{1}\right)<0$, and $\left\{x_{U}^{*}\right\}$ converges weak* to $x_{0}^{*}:=-e_{t_{0}} \in J\left(x_{0}\right) \cap y_{1}^{\perp}$. This proves that $A\left(x_{0}, 1\right) \neq \varnothing$.

Similarly, there exist a net $t_{U}^{\prime} \rightarrow t_{0}^{\prime}$ with $y_{1}\left(t_{U}^{\prime}\right)>0$ for all $U$ and functions $x_{U}^{\prime} \in C_{0}(t)$ with $x_{U}^{\prime} \rightarrow x_{0}$ such that

$$
x_{U}^{\prime}\left(t_{U}^{\prime}\right)-y_{1}\left(t_{U}^{\prime}\right)=\left\|x_{U}^{\prime}-y_{1}\right\|
$$

Then the functions $x_{U}^{* \prime}:=e_{t_{U}^{\prime}}$ are in ext $J\left(x_{U}^{\prime}-y_{1}\right), x_{U}^{* \prime}\left(-y_{1}\right)<0$, and $\left\{x_{U}^{* \prime}\right\}$ converges weak* to $x_{0}^{* \prime}:=e_{t_{0}} \in J\left(x_{0}\right) \cap y_{1}^{\perp}$. This proves that $A\left(x_{0},-1\right) \neq \varnothing$.

Case 1(ii). $t_{0} \in \overline{\left\{t \in T \mid y_{1}(t)>0\right\}}$ and $t_{0}^{\prime} \in\left\{t \in T \mid y_{1}(t)<0\right\}$.
Choose neighborhoods $U_{0}$ of $t_{0}$ and $U_{0}^{\prime}$ of $t_{0}^{\prime}$. By Urysohn's lemma, there exists $x_{0} \in C_{0}(T)$ so that $0 \geqslant x_{0} \geqslant\left(-1+y_{1}\right) \vee\left(-1-y_{1}\right), \quad x_{0}=0$ off $U_{0} \cup U_{0}^{\prime}$, and $x_{0}\left(t_{0}\right)=x_{0}\left(t_{0}^{\prime}\right)=-1$. Then $\left\|x_{0}\right\|=1$. Furthermore, just as in Case $1(i)$, it is easy to verify that $\left\|x_{0}\right\|=\left\|x_{0}-y_{1}\right\|=\left\|x_{0}+y_{1}\right\|$.

Let $\mathscr{U}$ denote the collection of all neighborhoods $U$ of $t_{0}$ ordered by inclusion. For each $U \in \mathscr{U}$, choose any $t_{U} \in U$ such that $y_{1}\left(t_{U}\right)>0$. Again, just as in the proof of Case $1(\mathrm{i})$, we obtain a net $\left\{x_{U}\right\}$ in $C_{0}(T)$ converging to $x_{0}$ and elements $x_{U}^{*}=-e_{\iota_{U}} \in \operatorname{ext} J\left(x_{U}+y_{1}\right)$ with $x_{U}^{*}\left(y_{1}\right)<0$ and $\left\{x_{U}^{*}\right\}$ weak* converges to some $x_{0}^{*}=-e_{t_{0}} \in J\left(x_{0}\right) \cap y_{1}^{\perp}$. Thus $A\left(x_{0}, 1\right) \neq \varnothing$.

Next let $\mathscr{U}^{\prime}$ denote the collection of all neighborhoods $U^{\prime}$ of $t_{0}^{\prime}$ ordered by inclusion. For each $U^{\prime} \in \mathscr{U}$, we can choose $t_{U^{\prime}} \in U^{\prime}$ such that $y_{1}\left(t_{U^{\prime}}\right)<0$. By Urysohn's lemma, choose $g_{U^{\prime}} \in C_{0}(T)$ such that $0 \leqslant g_{U^{\prime}} \leqslant 1, g_{U^{\prime}}\left(t_{U^{\prime}}\right)=1$, and $g_{U^{\prime}}=0$ off $U^{\prime}$. Then, arguing just as in Case 1, the function $x_{U^{\prime}}=$ $g_{U^{\prime}}\left[-1-x_{0}+y_{1}\right]+x_{0}$ is in $C_{0}(T), x_{U^{\prime}} \rightarrow x_{0}$, and $x_{U^{\prime}}\left(t_{U^{\prime}}\right)-y_{1}\left(t_{U^{\prime}}\right)=$
$-\left\|x_{U^{\prime}}-y_{1}\right\|$. Thus the functions $x_{U^{\prime \prime}}^{*}:=-e_{U^{\prime}}$ are in ext $J\left(x_{U^{\prime}}-y_{1}\right)$ and weak* converge to $x_{0}^{*}:=-e_{t_{0}^{\prime}} \in J\left(x_{0}\right) \cap y_{1}^{\perp}$. This proves that $A\left(x_{0},-1\right) \neq \varnothing$.

Case 2. bd $Z\left(y_{1}=\left\{t_{0}\right\}\right.$ and $y_{1}$ changes sign at $t_{0}$, i.e., $t_{0} \in$ $\overline{\left\{t \in T \mid y_{1}(t)>0\right\}} \cap\left\{t \in T \mid y_{1}(t)<0\right\}$.

Let $U_{0}$ be a neighborhood of $t_{0}$ and set $U_{0}^{\prime}=U_{0}$. Then by the exact same proof as in Case 1 (ii), we obtain $x_{0} \in C_{0}(T)$ with $\left\|x_{0}\right\|=\left\|x_{0}-y_{1}\right\|=$ $\left\|x_{0}+y_{1}\right\|, A\left(x_{0}, 1\right) \neq \varnothing$, and $A\left(x_{0}, 1\right) \neq \varnothing$.

In every case we have obtained an $x_{0} \in C_{0}(T)$ with $\left\|x_{0}\right\|=\left\|x_{0}-y_{1}\right\|=$ $\left\|x_{0}+y_{1}\right\|, A\left(x_{0},+1\right) \neq \varnothing$, and $A\left(x_{0},-1\right) \neq \varnothing$. By Theorem 4.5, $P_{\left[y_{1}\right]}$ does not have a continuous selection. That is, (1) fails.
$(2) \Rightarrow(1)$. Suppose (1) fails. Then by Theorem 4.5, there exists $x_{0} \in C_{0}(T)$ with $\left\|x_{0}\right\|=\left\|x_{0}-y_{1}\right\|=\left\|x_{0}+y_{1}\right\|$ such that $A\left(x_{0},+1\right) \neq \varnothing$ and $A\left(x_{0},-1\right) \neq \varnothing$. Since $A\left(x_{0},+1\right) \neq \varnothing$, there exist $x_{0}^{*} \in J\left(x_{0}\right) \cap y_{1}^{\perp}$ and a net $\left(x_{n}, \sigma_{n} e_{t_{n}}\right)$ in $C_{0}(T) \times C_{0}(T)^{*}$ with $x_{n} \rightarrow x_{0}, \sigma_{n}= \pm 1, \sigma_{n} e_{t_{n}} \in J\left(x_{n}+y_{1}\right)$, $\sigma_{n} e_{t_{n}} \rightarrow x_{0}^{*}$ weak $^{*}$, and $\sigma_{n} e_{t_{n}}\left(y_{1}\right)<0$ for all $n$. Since $x_{0}^{*} \neq 0$, it must be an extreme point so $x_{0}^{*}=\sigma_{0} e_{t_{0}}$ for some $\sigma_{0}= \pm 1, t_{0} \in T$. Since $\sigma_{n} e_{t_{n}}$ weak* converges to $\sigma_{0} e_{t_{0}}$, we must have $\sigma_{n} \rightarrow \sigma_{0}$ and $t_{n} \rightarrow t_{0}$. By passing to a subnet, we may assume that $\sigma_{n}=\sigma_{0}$ for all $n$. Since $x_{1}^{*} \in y_{1}^{\perp}$ and $\sigma_{0} y_{1}\left(t_{n}\right)<0$ for all $n$, it follows that $t_{0} \in \operatorname{bd} Z\left(y_{1}\right)$. Since $x_{0}^{*} \in J\left(x_{0}\right)$, we have $\sigma_{0} x_{0}\left(t_{0}\right)=\left\|x_{0}\right\|$ so $\sigma_{0}=\operatorname{sgn} x_{0}\left(t_{0}\right)$.

Similarly, since $A\left(x_{0},-1\right) \neq \varnothing$, there exist $x_{0}^{* \prime} \in J\left(x_{0}\right) \cap y_{1}^{\perp}$ and a net $\left(x_{n}^{\prime}, \sigma_{n} e_{t_{n}^{\prime}}^{\prime}\right.$ in $C_{0}(T) \times C_{0}(T)^{*}$ with $x_{n}^{\prime} \rightarrow x_{0}, \sigma_{n}= \pm 1, \sigma_{n} e_{t_{n}^{\prime}} \rightarrow x_{0}^{* \prime}$ weak*, $\sigma_{n} e_{t_{n}^{\prime}} \in J\left(x_{n}^{\prime}-y_{1}\right)$, and $\sigma_{n} e_{t_{n}^{\prime}}\left(-y_{1}\right)<0$ for all $n$. Arguing as above, we deduce that $x_{0}^{* \prime}=\sigma_{0}^{\prime} e_{t_{0}}, \sigma_{0}^{\prime}=\operatorname{sgn} x_{0}\left(t_{0}^{\prime}\right), t_{0}^{\prime} \in \operatorname{bd} Z\left(y_{1}\right), \sigma_{0}^{\prime} y_{1}\left(t_{n}^{\prime}\right)>0$ eventually, and $t_{n}^{\prime} \rightarrow t_{0}^{\prime}$. If $t_{0} \neq t_{0}^{\prime}$, then condition (2)(i) is violated. If $t_{0}=t_{0}^{\prime}$, then $\sigma_{0}=\sigma_{0}^{\prime}$ and $y_{1}\left(t_{n}\right) y_{1}\left(t_{n}^{\prime}\right)<0$ so $y_{1}$ changes sign at $t_{0}$. Thus condition (2)(ii) is violated. This proves that (2) fails.

It would be of interest to know whether an analogous result holds for any finite-dimensional subspace in $C_{0}(T)$.* In the special case when $T=[a, b]$, this has been accomplished as the culmination of a long series of papers by Nürnberger and Sommer (see their survey paper [12] and the references cited there).

When $T$ is any set with the discrete topology, the boundary of any subset of $T$ is empty and condition (2) of Theorem 5.1 is vacuously satisfied. In particular, if $T$ is the set of natural numbers with the discrete topology, then $C_{0}(T)=: c_{0}$ and we obtain the following corollary.

> 5.2. Corollary. The metric projection onto every one-dimensional subspace in $c_{0}$ has a continuous selection.

[^1]Actually, as a consequence of a result of Blatter [2], $c_{0}$ has the property $(\mathrm{P})$ of Brown [4]. Thus the metric projection onto any finite-dimensional subspace of $c_{0}$ is 1 .s.c. and hence has a continuous selection.

## 6. One-Dimensional Subspace in $L_{1}$

Let $(T, \mathscr{S}, \mu)$ be a measure space and let $L_{1}=L_{1}(T, \mathscr{P}, \mu)$ denote the Banach space of all integrable functions $x$ on $T$ with the norm

$$
\|x\|=\int_{T}|x| d \mu .
$$

The support of a function $x \in L_{1}$ is the set $\operatorname{supp} x:=\{t \in T \mid x(t) \neq 0\}$ and the zero set of $x$ is

$$
Z(x):=T \backslash \operatorname{supp} x=\{t \in T \mid x(t)=0\} .
$$

(Here, and in the sequel, all sets in $T$ are only defined up to a set of $\mu$-measure zero.) We shall assume that $L_{1}^{*}=L_{\infty}$. This will be the case, for example, if $(T, \mathscr{S}, \mu)$ is $\sigma$-finite.

A set $A \in \mathscr{S}$ is called an atom if $\mu(A)>0$ and either $\mu(B)=0$ or $\mu(B)=\mu(A)$ whenever $B \in \mathscr{S}$ and $B \subset A$.

The following lemma collects some facts about atoms that will be needed in this section.
6.1. Lemma. (1) For each $x \in L_{1}, \operatorname{supp}(x)$ is " $\sigma$-finite," i.e., is a countable union of sets having finite measure.
(2) There are at most a countable number of atoms in a $\sigma$-finite set, and each such atom has finite measure.
(3) A measurable function $x$ is constant a.e. ( $\mu$ ) on an atom $A$ of finite measure; this value will be denoted by $x(A)$.
(4) If $E \in \mathscr{Y}$ has the property that $0<\mu(E) \leqslant \infty$ and $E$ contains no atoms, then for each sequence of positive numbers $\left\{\varepsilon_{n}\right\}$ there exists a sequence of pairwise disjoint sets $\left\{E_{n}\right\}$ in $E$ with $0<\mu\left(E_{n}\right)<\varepsilon_{n}$ for every $n$.

These facts seem fairly well known with the possible exception of (4). However, (4) can be proved using the same idea as in the proof of Sak's lemma [6, pp. 308-309].
6.2. Definitions. A set $E \in \mathscr{S}$ will be called unifat if it is the union of a finite number of atoms. An element $y_{1} \in L_{1}$ is said to satisfy the Lazar condition if whenever $A$ and $B$ are disjoint sets in $\mathscr{S}$ with $A \cup B=\operatorname{supp}\left(y_{1}\right)$ and $\int_{A}\left|y_{1}\right| d \mu=\int_{B}\left|y_{1}\right| d \mu$, then one of the sets $A$ or $B$ must be unifat.

The main result of this section is the following intrinsic characterization of those one-dimensional subspaces in $L_{1}$ whose metric projections admit continuous selections.
6.3. Theorem. Let $y_{1} \in L_{1} \backslash\{0\}$. Then $P_{\left[y_{1}\right]}$ has a continuous selection if and only if $y_{1}$ satisfies the Lazar condition.

Before giving the proof, we observe a few immediate corollaries of this theorem.
6.4. Corollary. If $\operatorname{supp}\left(y_{1}\right)$ contains no atoms, then $P_{\left[y_{1}\right]}$ does not have a continuous selection.

Related to this corollary, Lazar, Morris, and Wulbert [10] proved that if $T$ contained no atoms, then the metric projection onto any finite-dimensional subspace in $L_{1}(T, \mathscr{S}, \mu)$ does not have a continuous selection.
6.5. Corollary. If $\operatorname{supp}\left(y_{1}\right)$ is a finite union of atoms, then $P_{\left[y_{1}\right]}$ has a continuous selection. In particular, if $L_{1}$ is finite dimensional, the metric projection onto any one-dimensional subspace has a continuous selection.

The next corollary is due to Lazar and provided the motivation for the name "Lazar condition." It follows immediately from Theorem 6.3 taking $T=\mathbf{N}=$ "the natural numbers," $\mathscr{S}$ all subsets of $\mathbf{N}$, and $\mu$ counting measure on $\mathscr{S}$, i.e., $\mu(E)=\operatorname{card}(E)$. Then $L_{1}(T, \mathscr{S}, \mu)=l_{1}$ and Theorem 6.3 reduces to
6.6. Corollary (Lazar [9]). Let $y_{1} \in l_{1} \backslash\{0\}$. Then $P_{\left[y_{1}\right]}$ has a continuous selection if and only if whenever $A$ and $B$ are disjoint sets of integers with

$$
A \cup B=\left\{i \in \mathbf{N} \mid y_{1}(i) \neq 0\right\}
$$

and

$$
\sum_{i \in A}\left|y_{1}(i)\right|=\sum_{i \in B}\left|y_{1}(i)\right|
$$

then either A or B must be finite.
The remainder of this section is devoted to a proof of Theorem 6.3.
6.7. Lemma. Let $T_{1}$ be a $\sigma$-finite subset of $T$. If $T_{1}$ is not unifat, then there exists a sequence $\left\{E_{n}\right\}$ of pairwise disjoint subsets of $T_{1}$ with $0<\mu\left(E_{n}\right)<\infty$ such that, for any $x \in L_{1}$,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \int_{E_{n}}|x| d \mu=0 \tag{6.7.1}
\end{equation*}
$$

Proof. Since $T_{1}$ is not unifat, either $T_{1}$ is the union of a countable infinity of atoms, or $\mu\left(T_{1} \backslash A\right)>0$, where $A$ is the union of all atoms in $T_{1}$. In the latter case, we set $E=T_{1} \backslash A$ and apply Lemma 6.1(4). This yields a sequence $\left\{E_{n}\right\}$ of pairwise disjoint subsets of $T$ with $\lim _{n \rightarrow \infty} \mu\left(E_{n}\right)=0$. For any $x \in L_{1}$, the condition (6.7.1) is a well-known consequence of the monotone convergence theorem.

In the former case, we have

$$
T_{1}=\bigcup_{1}^{\infty} A_{n}
$$

where $\left\{A_{n}\right\}$ is a sequence of pairwise disjoint atoms. Now for each $x \in L_{1}$,

$$
\sum_{1}^{\infty}\left|x\left(A_{n}\right)\right| \mu\left(A_{n}\right)=\int_{U_{1}^{\infty} A_{n}}|x| d \mu \leqslant \int_{T}|x| d \mu=\|x\|<\infty
$$

so $\lim _{n \rightarrow \infty}\left|x\left(A_{n}\right)\right| \mu\left(A_{n}\right)=0$. Hence

$$
\int_{A_{n}}|x| d \mu=\left|x\left(A_{n}\right)\right| \mu\left(A_{n}\right) \rightarrow 0 .
$$

Setting $E_{n}=A_{n}$ for all $n$, the result follows.
It is well known that $\operatorname{ext}\left(L_{\infty}\right)$ consists of all those measurable functions $f$ on $T$ such that $|f|=1$ a.e. $(\mu)$. Also, for each $x^{*} \in L_{1}^{*}$, there is a unique $f \in L_{\infty}$ such that

$$
x^{*}(x)=\int_{T} x f d \mu, \quad x \in L_{1}
$$

and $\left\|x^{*}\right\|=$ ess supp $|f|$. We shall call $f$ the representer of $x^{*}$.
6.8. Lemma. Let $y_{1} \in L_{1} \backslash\{0\}$ and let $x_{0} \in L_{1}$ satisfy

$$
\begin{equation*}
\left\|x_{0}\right\|=\left\|x_{0}+y_{1}\right\|=\left\|x_{0}-y_{1}\right\| . \tag{6.8.1}
\end{equation*}
$$

Let $x_{0}^{*} \in y_{1}^{\perp} \cap J\left(x_{0}\right)$, suppose $f_{0} \in L_{\infty}$ is the representer of $x_{0}^{*}$, and define

$$
\begin{aligned}
& T^{+}:=\left\{t \in \operatorname{supp} y_{1} \mid f_{0}(t)=\operatorname{sgn} y_{1}(t)\right\} \\
& T^{-}:=\left\{t \in \operatorname{supp} y_{1} \mid f_{0}(t)=-\operatorname{sgn} y_{1}(t)\right\} .
\end{aligned}
$$

Then:
(1) $\operatorname{supp} f_{0} \supset \operatorname{supp} x_{0} \supset \operatorname{supp} y_{1}$ and $\operatorname{supp} y_{1}=T^{+} \cup T^{-}$.
(2) $T^{+} \subset \operatorname{supp}\left(x_{0}+y_{1}\right), T^{-} \subset \operatorname{supp}\left(x_{0}-y_{1}\right)$.
(3) If $T^{+}$is unifat, then $x_{0}^{*} \notin A\left(x_{0}, 1\right)$; if $T^{-}$is unifat, then $x_{0}^{*} \notin A\left(x_{0},-1\right)$.

Proof. (1) By (6.8.1), it follows that $x_{0}^{*} \in J\left(x_{0}-y_{1}\right) \cap J\left(x_{0}+y_{1}\right)$. Thus

$$
\int_{T} x_{0} f_{0} d \mu=\left\|x_{0}\right\| \quad \text { and } \quad \int_{T}\left(x_{0} \pm y_{1}\right) f_{0} d \mu=\left\|x_{0} \pm y_{1}\right\|
$$

implies that

$$
f_{0}(t)= \begin{cases}\operatorname{sign} x_{0}(t) & \text { a.e. on } \operatorname{supp} x_{0}  \tag{6.8.2}\\ \operatorname{sgn}\left[x_{0}(t)+y_{1}(t)\right] & \text { a.e. on } \operatorname{supp}\left(x_{0}+y_{1}\right) \\ \operatorname{sgn}\left[x_{0}(t)-y_{1}(t)\right] & \text { a.e. on } \operatorname{supp}\left(x_{0}-y_{1}\right)\end{cases}
$$

Hence if $t \in \operatorname{supp} y_{1} \backslash \operatorname{supp} x_{0}$, we have that

$$
f_{0}(t)=\operatorname{sgn} y_{1}(t)=-\operatorname{sgn} y_{1}(t),
$$

which is impossible. Hence

$$
\mu\left(\operatorname{supp} y_{1} \backslash \operatorname{supp} x_{0}\right)=0,
$$

or supp $y_{1} \subset \operatorname{supp} x_{0}$. Also, since $f_{0}(t)=\operatorname{sgn} x_{0}(t)$ on $\operatorname{supp} x_{0}$, it follows that $\operatorname{supp} x_{0} \subset \operatorname{supp} f_{0}$. Finally, if $t \in \operatorname{supp} y_{1}$, then $f_{0}(t)= \pm 1$ so supp $y_{1}=T^{+} \cup T^{-}$.
(2) If $t \in T^{+}$, then $t \in \operatorname{supp} y_{1}$ and $f_{0}(t)=\operatorname{sgn} y_{1}(t)$. But supp $y_{1} \subset$ $\operatorname{supp} x_{0}$ and $f_{0}(t)=\operatorname{sgn} x_{0}(t)$. Thus $y_{1}(t) x_{0}(t)>0$ and $t \in \operatorname{supp}\left(x_{0}+y_{1}\right)$. That is, $T^{+} \subset \operatorname{supp}\left(x_{0}+y_{1}\right)$. Similarly, $T^{-} \subset \operatorname{supp}\left(x_{0}-y_{1}\right)$.
(3) Assume $T^{+}$is unifat. Then $T^{+}=\bigcup_{1}^{k} A_{i}$, where the $A_{i}$ are pairwise disjoint atoms and $0<\mu\left(A_{i}\right)<\infty$. To show that $x_{0}^{*} \notin A\left(x_{0}, 1\right)$, it suffices to show that if $\left\{\left(x_{n}, x_{n}^{*}\right)\right\}$ is any net in $L_{1} \times L_{1}^{*}$ with $x_{n} \rightarrow x_{0}, x_{n}^{*} \rightarrow x_{0}^{*}$ weak ${ }^{*}$, and $x_{n}^{*} \in J\left(x_{n}+y_{1}\right)$, then $x_{n}^{*}\left(y_{1}\right) \geqslant 0$ eventually. Let $\left\{\left(x_{n}, x_{n}^{*}\right)\right\}$ be such a net and let $f_{n} \in L_{\infty}$ be the representer of $x_{n}^{*}$. Since $T^{+} \subset \operatorname{supp}\left(x_{0}+y_{1}\right)$ by (2), it follows that $x_{0}\left(A_{i}\right)+y_{1}\left(A_{i}\right) \neq 0$ for $i=1,2, \ldots, k$. Since $x_{n}+y_{1} \rightarrow x_{0}+y_{1}$, it follows that $x_{n}\left(A_{i}\right)+y_{1}\left(A_{i}\right) \rightarrow x_{0}\left(A_{i}\right)+y_{1}\left(A_{i}\right)$ so $x_{n}\left(A_{i}\right)+y_{1}\left(A_{i}\right) \neq 0$ eventually (for $\left.i=1,2, \ldots, k\right)$. Since $x_{n}^{*} \in J\left(x_{n}+y_{1}\right)$,

$$
\begin{aligned}
f_{n}\left(A_{i}\right) & =\operatorname{sgn}\left[x_{n}\left(A_{i}\right)+y_{1}\left(A_{i}\right)\right] & & \\
& =\operatorname{sign}\left[x_{0}\left(A_{i}\right)+y_{1}\left(A_{i}\right)\right] & & \text { eventually } \\
& =f_{0}\left(A_{i}\right) & & \text { by }(6.8 .2)
\end{aligned}
$$

That is, $f_{n}=f_{0}$ eventually on $T^{+}$. Hence, for $n$ eventually,

$$
\begin{aligned}
x_{n}^{*}\left(y_{1}\right) & =\int_{T} f_{n} y_{1} d \mu=\int_{T^{+} \cup T^{-}} f_{n} y_{1} d \mu \\
& =\int_{T^{+}} f_{0} y_{1} d \mu+\int_{T^{-}} f_{n} y_{1} d \mu \\
& \geqslant \int_{T^{+}} f_{0} y_{1} d \mu-\int_{T^{-}}\left|y_{1}\right| d \mu=\int_{T^{+}} f_{0} y_{1} d \mu+\int_{T^{-}} f_{0} y_{1} d \mu \\
& =\int_{T^{+} \cup T^{-}} f_{0} y_{1} d \mu=x_{0}^{*}\left(y_{1}\right)=0 .
\end{aligned}
$$

Thus $x_{0}^{*} \notin A\left(x_{0}, 1\right)$.
Similarly, if $T^{-}$is unifat, then $x_{0}^{*} \notin A\left(x_{0},-1\right)$.
Now we are in position to prove Theorem 6.3.
Proof of Theorem 6.3. Suppose $y_{1}$ fails the Lazar condition. We will show that there exists $x_{0} \in L_{1}$ with $\left\|x_{0}\right\|=\left\|x_{0}-y_{1}\right\|=\left\|x_{0}+y_{1}\right\|$ such that $A\left(x_{0}, 1\right) \neq \varnothing$ and $A\left(x_{0},-1\right) \neq \varnothing$. The assumption on $y_{1}$ implies that there exist disjoint sets $A$ and $B$ such that $A \cup B=\operatorname{supp} y_{1}, \int_{A}\left|y_{1}\right| d \mu=$ $\int_{B}\left|y_{1}\right| d \mu$, and neither $A$ nor $B$ is unifat. By Lemma 6.7, there exist sequences $\left\{E_{n}\right\}$ and $\left\{F_{n}\right\}$ of pairwise disjoint sets such that $E_{n} \subset A, F_{n} \subset B$, $0<\mu\left(E_{n}\right)<\infty, 0<\mu\left(F_{n}\right)<\infty$, and, for each $x \in L_{1}$,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \int_{E_{n}}|x| d \mu=0=\lim _{n \rightarrow \infty} \int_{F_{n}}|x| d \mu . \tag{6.3.1}
\end{equation*}
$$

Define functions $f_{0}$ and $x_{0}$ on $T$ by

$$
f_{0}(t)= \begin{cases}\operatorname{sgn} y_{1}(t) & \text { for } t \in A \\ -\operatorname{sgn} y_{1}(t) & \text { for } t \in B \\ 1 & \text { otherwise }\end{cases}
$$

and

$$
x_{0}(t)= \begin{cases}y_{1}(t) & \text { for } t \in A \\ -y_{1}(t) & \text { for } t \in B \\ 0 & \text { otherwise }\end{cases}
$$

Then $f_{0} \in L_{\infty}$, ess sup $\left|f_{0}\right|=1$, and $x_{0} \in L_{1}$. A simple computation shows that

$$
\left\|x_{0}\right\|=\left\|x_{0}-y_{1}\right\|=\left\|x_{0}+y_{1}\right\| \quad\left(=\left\|y_{1}\right\|\right)
$$

and, letting $f_{0}$ be the representer of the functional $x_{0}^{*} \in L_{1}^{*}$, we see that $x_{0}^{*} \in y_{1}^{\perp} \cap J\left(x_{0}\right)$ and $x_{0}^{*} \in \operatorname{ext}\left(L_{1}^{*}\right)_{1}$.

Next define functions $f_{n}$ in $L_{\infty}$ by

$$
f_{n}=\left\{\begin{array}{lll}
f_{0} & \text { on } & T \backslash E_{n} \\
-f_{0} & \text { on } & E_{n}
\end{array}\right.
$$

and functions $x_{n}$ in $L_{1}$ by

$$
x_{n}=\left\{\begin{array}{lll}
x_{0} & \text { on } & T \backslash E_{n} \\
-2 y_{1} & \text { on } & E_{n} .
\end{array}\right.
$$

Let $f_{n}$ be the representer of $x_{n}^{*} \in L_{1}^{*}$. Then $x_{n}^{*} \in \operatorname{ext}\left(L_{1}\right)_{1}$ and a straightforward computation verifies that

$$
x_{n}^{*}\left(x_{n}+y_{1}\right)=\left\|x_{0}\right\|-\int_{E_{n}}\left|y_{n}\right| d \mu=\left\|x_{n}+y_{1}\right\| .
$$

That is, $x_{n}^{*} \in \operatorname{ext} J\left(x_{n}+y_{1}\right)$. Next observe that

$$
\left\|x_{n}-x_{0}\right\|=3 \int_{E_{n}}\left|y_{1}\right| d \mu \rightarrow 0
$$

by (6.3.1). Further, for any $x \in L_{1}$,

$$
\begin{aligned}
x_{n}^{*}(x) & =\int_{T} f_{n} x d \mu=\int_{T \backslash E_{n}} f_{0} x d \mu-\int_{E_{n}} f_{0} x d \mu \\
& =\int_{T} f_{0} x d \mu-2 \int_{E_{n}} f_{0} x d \mu=x_{0}^{*}(x)-2 \int_{E_{n}} f_{0} x d \mu \\
& \rightarrow x_{0}^{*}(x) \quad \text { by (6.3.1). }
\end{aligned}
$$

That is, $x_{n}^{*} \rightarrow x_{0}^{*}$ weak*. Finally,

$$
\begin{aligned}
x_{n}^{*}\left(y_{1}\right) & =\int_{T} f_{n} y_{1} d \mu=\int_{T \backslash E_{n}} f_{0} y_{1} d \mu-\int_{E_{n}} f_{0} y_{1} d \mu \\
& =\int_{T} f_{0} y_{1} d \mu-2 \int_{E_{n}} f_{0} y_{1} d \mu \\
& =-2 \int_{E_{n}}\left|y_{1}\right| d \mu<0
\end{aligned}
$$

This proves that $x_{0}^{*} \in A\left(x_{0}, 1\right)$.

Similarly, defining $f_{n}^{\prime}$ and $x_{n}^{\prime}$ on $T$ by

$$
f_{n}^{\prime}=\left\{\begin{array}{ll}
f_{0} & \text { on } T \backslash F_{n} \\
-f_{0} & \text { on } F_{n}
\end{array} \quad x_{n}^{\prime}= \begin{cases}x_{0} & \text { on } T \backslash F_{n} \\
2 y_{1} & \text { on } F_{n}\end{cases}\right.
$$

and letting $f_{n}^{\prime}$ be the representers for the functionals $x_{n}^{* \prime}$, we can prove that $\left(x_{n}^{\prime}, x_{n}^{* \prime}\right) \rightarrow\left(x_{0}, x_{0}^{*}\right), x_{n}^{* \prime} \in \operatorname{ext} J\left(x_{n}^{\prime}-y_{1}\right)$, and $x_{n}^{* \prime}\left(-y_{1}\right)<0$ for all $n$. Thus $x_{0}^{*} \in A\left(x_{0},-1\right)$. By Theorem 4.5, it follows that $P_{\left[y_{1}\right]}$ does not have a continuous selection.

Conversely, suppose $P_{[y]]}$ fails to have a continuous selection. Then by Theorem 4.5 there exists $x_{0} \in L_{1}$ with

$$
\left\|x_{0}\right\|=\left\|x_{0}-y_{1}\right\|=\left\|x_{0}+y_{1}\right\|
$$

such that $A\left(x_{0},+1\right) \neq \varnothing$ and $A\left(x_{0},-1\right) \neq \varnothing$. For each $\sigma \in\{+1,-1\}$, let $x_{\sigma}^{*} \in A\left(x_{0}, \sigma\right)$ and let $f_{\sigma} \in L_{\infty}$ be the representer of $x_{\sigma}^{*}$. Define

$$
\begin{aligned}
& T_{1}(\sigma):=\left\{t \in \operatorname{supp} y_{1} \mid f_{\sigma}(t)=\operatorname{sgn} y_{1}(t)\right\} \\
& T_{2}(\sigma):=\left\{t \in \operatorname{supp} y_{1} \mid f_{\sigma}(t)=-\operatorname{sgn} y_{1}(t)\right\} .
\end{aligned}
$$

Since $x_{\sigma}^{*} \in y_{1}^{\perp} \cap J\left(x_{0}\right)$, Lemma 6.8 implies that

$$
\begin{gather*}
\operatorname{supp} f_{\sigma} \supset \operatorname{supp} x_{0} \supset \operatorname{supp} y_{1}, \\
T_{1}(\sigma) \cup T_{2}(\sigma)=\operatorname{supp} y_{1} \quad \text { and } \quad T_{1}(\sigma) \cap T_{2}(\sigma)=\varnothing . \tag{6.3.2}
\end{gather*}
$$

Further, $x_{\sigma}^{*} \in y_{1}^{\perp}$ implies that

$$
\int_{T_{1}(\sigma)}\left|y_{1}\right| d \mu=\int_{T_{2}(\sigma)}\left|y_{1}\right| d \mu
$$

If $y_{1}$ has the Lazar condition, then for each $\sigma \in\{+1,-1\}$ either $T_{1}(\sigma)$ or $T_{2}(\sigma)$ is unifat. If $\sigma=1$, then since $x_{1}^{*} \in A\left(x_{0},+1\right)$, it follows by Lemma 6.8(3) that $T_{1}(1)$ is not unifat. Hence $T_{2}(1)$ is unifat. Similarly, since $x_{-1}^{*} \in A\left(x_{0},-1\right), T_{2}(-1)$ is not unifat and $T_{1}(-1)$ is unifat. Since $x_{\sigma}^{*} \in J\left(x_{0}\right)$ for $\sigma= \pm 1$, it follows that

$$
f_{1}(t)=\operatorname{sgn} x_{0}(t)=f_{-1}(t)
$$

for all $t \in \operatorname{supp} x_{0} \supset \operatorname{supp} y_{1}$. Thus $T_{1}(1) \cap T_{2}(-1)=\varnothing \quad$ and $T_{1}(-1) \cap T_{2}(1)=\varnothing$. But this implies by (6.3.2) that $T_{2}(-1) \subset T_{2}(1)$ and $T_{2}(1) \subset T_{2}(-1)$. That is, $T_{2}(-1)=T_{2}(1)$. But $T_{2}(1)$ is unifat and $T_{2}(-1)$ is not unifat. This contradiction shows that $y_{1}$ fails to have the Lazar condition, and completes the proof.

It would be interesting to know whether there is an analogue of Theorem 6.3 for subspaces of $L_{1}$ of any finite dimension greater than one.

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[^0]:    * The work of the second (resp. third) author was performed while she (resp. he) was a visiting scholar at The Pennsylvania State University during the period April 1983 through June 1985 (resp. August 1983 through August 1984).

[^1]:    * Wu Li has recently produced such a result in the case when $T$ is locally connected.

